

I-1) calc Pop diff For:

i) ^{13}C @ 7T, 300K

$$\omega_0 = \gamma B_0 = \frac{470.8 \text{ rad}}{\text{sec}} \times 10^6$$

$$\nu_0 = \frac{\omega_0}{2\pi} = \frac{75 \times 10^6 \text{ cycles}}{\text{sec}}$$

$$S = 1/2$$

$$k = 1.38 \times 10^{-23} \text{ J/K}$$

$$\gamma_c = \frac{67.262 \left(\frac{\text{rad}}{\text{S.T}} \right) \times 10^6}{\text{sec}}$$

$$h = 6.626 \times 10^{-34} \text{ J.s}$$

$$T = 300 \text{ K}$$

$$kT = 4.14 \times 10^{-21}$$

Calculate excess on relation to N_T

~~$$kT = 1.987 \times 10^{-21} \text{ J}$$~~

$$\therefore \frac{N_2 - N_1}{N_T} =$$

$$\frac{h\omega_0}{2kT} = \frac{h\nu}{2kT} =$$

$$N_2 - N_1 = \frac{N_T}{2} \left(1 + \frac{h\omega_0}{2kT} \right) - \frac{N_T}{2} \left(1 - \frac{h\omega_0}{2kT} \right)$$

$$\gamma = \frac{q}{2m} \times g \mu_N$$

$$\Rightarrow \frac{N_2 - N_1}{N_T} = \frac{1}{2} + \frac{h\omega_0}{4kT} - \frac{1}{2} + \frac{h\omega_0}{4kT}$$

$$\frac{N_2 - N_1}{N_T} = \frac{h\omega_0}{2kT} = \frac{h\nu}{2kT} =$$

$$\frac{6.626 \times 10^{-34} \times 75 \times 10^6}{2 \times 4.14 \times 10^{-21}} = \frac{4.97 \times 10^{-26}}{8.28 \times 10^{-21}} =$$

$$\frac{h\nu}{2kT} = 112 \times 10^{-5} \approx \frac{1}{10000}$$

ii) $25 \text{ Mg} @ 7T, 300K$

~~$$\frac{25 \times 6.626 \times 10^{-34}}{2 \times 4.14 \times 10^{-21}} = \frac{2 \times 10^{-6}}{1,000,000} \approx 2$$~~

$\gamma =$

$h\nu = 25 \text{ MHz}$

$S = \frac{5}{2}$

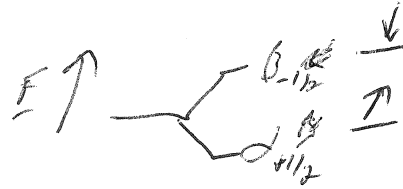
ii)

$$N_D = \frac{N_T}{2S+1} \left(1 + m_g \frac{\hbar \omega_0}{kT} \right)$$

$$S = \frac{5}{2}$$

$$m_g = \frac{5}{2} \frac{3}{2} \frac{1}{2} \frac{-1-3}{2} \frac{-5}{2}$$

$$N_g = \frac{N_T}{6} \left(1 + m_g \frac{\hbar \omega_0}{kT} \right)$$



$$E_{5/2} - E_{-5/2} \Rightarrow \frac{N_{5/2}}{2} - \frac{N_{-5/2}}{2} = \frac{N_T}{6} \left(1 + \frac{5\hbar \omega_0}{2kT} \right) - \frac{N_T}{6} \left(1 - \frac{5\hbar \omega_0}{2kT} \right)$$

$$\Rightarrow \frac{\Delta N_{5/2}}{N_T} = \frac{1}{6} \left(1 - 1 + \frac{5\hbar \omega_0}{2} + \frac{5\hbar \omega_0}{2kT} \right)$$

$$= \frac{1}{6} \left(\frac{10\hbar \omega_0}{2kT} \right) = \frac{5\hbar \omega_0}{6kT}$$

or for just $m=1$

$$E_{5/2} - E_{3/2} \Rightarrow \frac{N_{5/2}}{2} - \frac{N_{3/2}}{2} = \frac{N_T}{6} \left(1 + \frac{5\hbar \omega_0}{2kT} \right) - \frac{N_T}{6} \left(1 + \frac{3\hbar \omega_0}{2kT} \right)$$

$$\frac{\Delta N}{N_T} = \frac{1}{6} \left[1 + \frac{5x}{2} - 1 - \frac{3x}{2} \right] = \frac{1}{6} x = \frac{1}{6} \left(\frac{\hbar \omega_0}{2kT} \right)$$

$$\therefore \frac{5-3}{2} \Rightarrow \frac{1}{6} \left(\frac{6.626e^{-34} \times 25e^6}{2 \times 4.14e^{-21}} \right) = 3.3e^{-7}$$

* NOTE all ± 1 transitions have same pop diff

$$N_2 = \frac{N_T}{2} \left(1 + \frac{\hbar \omega_0}{2kT} \right) \quad N_3 = \frac{N_T}{2} \left(1 - \frac{\hbar \omega_0}{2kT} \right)$$

$$E \uparrow \quad \begin{aligned} E_3 &= \frac{1}{2} \hbar \omega_0 \\ E_2 &= -\frac{1}{2} \hbar \omega_0 \end{aligned}$$

$$\bar{M} = \gamma \hbar \bar{S}$$

$$E = -\bar{M} \cdot \bar{B}_0 = -\gamma \hbar S_z B_0 \quad \therefore E_2 =$$

$$\omega_0 = \omega_0$$

$$\begin{aligned} E &= -\hbar S_z \gamma B_0 \\ E &= -\hbar S_z \omega_0 \end{aligned}$$

$$S_z | \uparrow \rangle = \frac{1}{2} \hbar | \uparrow \rangle$$

$$S_z | \downarrow \rangle = -\frac{1}{2} \hbar | \downarrow \rangle$$

$$\begin{aligned} E_3 & \downarrow \downarrow \downarrow \downarrow \quad N_3 = e^{-E_3/kT} \\ E_2 & \uparrow \uparrow \uparrow \uparrow \quad N_2 = e^{-E_2/kT} \end{aligned}$$

$$\frac{N_3}{N_2} = \frac{e^{-E_3/kT}}{e^{-E_2/kT}} = e^{-(E_3 - E_2)/kT} = e^{-\hbar \omega_0/kT}$$

expand

$$\frac{N_3}{N_2} = e^{-\hbar \omega_0/kT} = 1 - \frac{\hbar \omega_0}{kT}$$

$$N_T = N_2 + N_3$$

$$N_2 = N_T - N_3$$

$$N_3 = (N_T - N_3) \left(1 - \frac{\hbar \omega_0}{kT} \right)$$

$$N_3 = (N_T - N_3) \left(1 - \frac{\hbar \omega_0}{kT} \right)$$

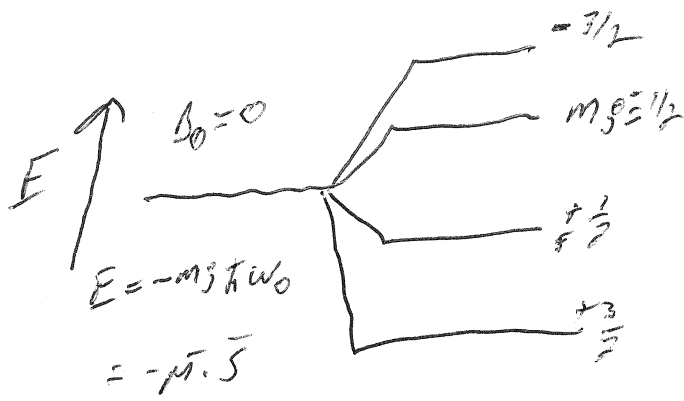
$$= N_T - N_T \left(\frac{\hbar \omega_0}{kT} \right) - N_3 + N_3 \frac{\hbar \omega_0}{kT}$$

$$\partial N_3 = N_T - N_T \left(\frac{\hbar \omega_0}{kT} \right) = \dots$$

$$\therefore \begin{aligned} N_3 &= \frac{N_T}{2} \left(1 - \frac{\hbar \omega_0}{2kT} \right) \\ N_2 &= \frac{N_T}{2} \left(1 + \frac{\hbar \omega_0}{2kT} \right) \end{aligned}$$

General Form:

$$M_s \quad (-S \leq m_s \leq S)$$



$$S = \frac{3}{2}$$

$B_0 \neq 0$

$$m_s = \frac{-3}{2}, \frac{-1}{2}, \frac{1}{2}, \frac{3}{2}$$

General Pop eqn

$$N_j^0 = \frac{N_T}{2S+1} \left(1 + \frac{m_s \hbar \omega_0}{kT} \right)$$

w

$$I-7) \frac{\Delta N}{N_T}(C) = \frac{1}{10000} @ 298K$$

$$T = 298K$$

$$\nu_{Mg} = 25 MHz$$

$$\nu_C = 75 MHz$$

at what temp does the Mg sample need to be to have same $\frac{\Delta N}{N} @ (\pm 1/2)$ transition? note, $Mg = 10K C$ in natural abundance

$$kT = 4.1e^{-21}$$

$$h = 6.626e^{-34} J s$$

$$k = 1.38e^{-23} J/K$$

$$@ 300K \quad Mg \frac{3/2}{5/2} \Rightarrow \frac{\Delta N}{N_T} = 3.3e^{-7}$$

$$\Delta N_{1/2} = \frac{N_T}{6} \left(1 + \frac{h\nu}{2kT}\right) - \frac{N_T}{6} \left(1 - \frac{h\nu}{2kT}\right)$$

$$\frac{\Delta N_{1/2}}{N_T} = \frac{h\nu_0}{6kT} \quad \left. \vphantom{\frac{\Delta N_{1/2}}{N_T}} \right\} Mg \left(\frac{1}{2} - \frac{1}{6}\right)$$

$$\frac{\Delta N_{1/2}}{N_C} = \frac{h\nu_0}{2kT} \quad \left. \vphantom{\frac{\Delta N_{1/2}}{N_C}} \right\} C$$

$$\frac{10 * h\nu}{6kT} = \frac{1}{10,000}$$

$$T = \frac{10 * h\nu}{6k} = \frac{1.66e^{-21}}{6k} = 20K$$

check $\frac{\Delta N_{1/2}}{N_T} = \frac{h * 25e^6}{6kT} = \frac{6.626e^{-34} * 25e^6}{6 * 4.1e^{-21} * k * 20} = \frac{1.656e^{-26}}{12 * 120k} = \frac{1}{100,000}$

* 10
NAT
Abund diff $\Rightarrow \frac{\Delta N_{1/2}}{N_T} = \frac{1}{10,000} \quad \checkmark @ 20K$

III-3) start from here

$$N_j^0 = \frac{N_T}{2S+1} \left(1 + \frac{m_j \hbar \omega_0}{kT} \right)$$

eg) $S = 3/2$

$$m_j = (-S \leq m_j \leq S)$$

$$m_j = -\frac{3}{2}, -\frac{1}{2}, \frac{1}{2}, \frac{3}{2}$$

$$\omega = \gamma b_0$$

$$E = -\vec{\mu} \cdot \vec{B}$$

$$M = \gamma \hbar S_z$$

$$\therefore E = -\gamma \hbar b_0 S_z$$

$$E_j = -\hbar \omega_0 S_z$$

$$\vec{M}_0 =$$

$$\vec{M}_0 = \sum_j \vec{M}_j \cdot N_j^0$$

$$M = \gamma \hbar S_z$$

$$= \hbar \gamma S_z$$

$$M = \gamma \hbar S_z$$

$$= m_j \hbar \gamma$$

$$\vec{M}_0 = \sum_j (m_j \gamma \hbar) \left[\frac{N_T}{2S+1} \left(1 + \frac{m_j \hbar \omega_0}{kT} \right) \right]$$

$$= \sum_j \left[\frac{N_T (m_j \gamma \hbar)}{2S+1} + \frac{N_T (m_j \gamma \hbar) (m_j \hbar \gamma b_0)}{(2S+1) kT} \right]$$

NOTE $\sum_j N_T m_j \gamma \hbar = C m_j = \frac{-1}{2} + \frac{1}{2} = 0$
 $= \frac{-3}{2} + \frac{-1}{2} + \frac{1}{2} + \frac{3}{2} = 0 \therefore$ cancels out

$$M_0 = \sum_j \left(\frac{N_T}{2S+1} \right) \left(\frac{m_j^2 \gamma^2 \hbar^2 b_0}{kT} \right)$$

$$S = 1/2 \Rightarrow M_0 = \sum_s \frac{N_T}{2} [m_s^2(C)]$$

$$M_0 = \frac{N_T}{2} \left[\left(\frac{1}{2}\right)^2 C + \left(\frac{-1}{2}\right)^2 C \right] = \frac{N_T}{2} \left[\frac{1}{4} C + \frac{1}{4} C \right]$$

$$C = \frac{\gamma^2 \hbar^2 b_0}{kT}$$

$$= \frac{N_T}{2} \left(\frac{C}{2} \right) = \frac{N_T}{2} \left[\frac{\gamma^2 \hbar^2 b_0}{2kT} \right]$$

$$M_0(1/2) = \frac{N_T \gamma^2 \hbar^2 b_0}{4kT}$$

Curie's Law

$M_0 \Rightarrow$ linear depend on N_T, b_0

\Rightarrow inversely to Temp

\Rightarrow Quadratic to γ !

$$S = \frac{3}{2}$$

$$M_0 = \sum_s C m_s^2$$

$$= \left[\left(\frac{3}{2}\right)^2 + \left(\frac{1}{2}\right)^2 + \left(\frac{-1}{2}\right)^2 + \left(\frac{-3}{2}\right)^2 \right] C$$

$$= \left[\frac{9}{4} + \frac{1}{4} + \frac{1}{4} + \frac{9}{4} \right] C$$

$$= \frac{20}{4} C = 5C = 5 \left[\frac{N_T \gamma^2 \hbar^2 b_0}{(2S+1)kT} \right]$$

$$M_0\left(\frac{3}{2}\right) = \frac{5}{4} \left[\frac{N_T \gamma^2 \hbar^2 b_0}{kT} \right]$$

$$2\left(\frac{3}{2}\right) + 1 = 4$$

$\hookrightarrow 5 \times^5$ more sensitive than $S = \frac{1}{2}$
(behave lot diff)

$$I-4) \langle m | \hat{A} | n \rangle = \langle n | \hat{A}^\dagger | m \rangle^*$$

$$\hat{0} = \hat{0}^\dagger$$

$$\hat{0}_{ij} = \begin{pmatrix} \hat{0} & \\ & \hat{0}_{ji} \end{pmatrix}^* \quad \left(\begin{array}{l} \text{transpose} \\ \& \text{cc} \end{array} \right)$$

$$\hat{0}_{ij} = (\hat{0}_{ji})^* \Rightarrow \text{Real / Hermitian}$$

$$\langle \hat{0} | \hat{0}^\dagger | \hat{0} \rangle = \hat{0}_{\hat{0}\hat{0}}$$

$$1) \langle \hat{0} | \hat{0}^\dagger | \hat{0} \rangle = a_j \langle \hat{0} | \hat{0} \rangle$$

$$\text{NOTE } \langle \hat{0} | = | \hat{0} \rangle^*$$

$$2) \langle \hat{j} | \hat{0}^\dagger | \hat{0} \rangle^* = \langle \hat{0} | \hat{0}^\dagger | \hat{j} \rangle$$

$$= a_j^* \langle \hat{0} | \hat{0} \rangle$$

$$\langle \hat{j} | = | \hat{j} \rangle^*$$

$$\langle \hat{j} | = | \hat{j} \rangle^*$$

$$f_{ij} = \langle \hat{0} | \hat{0} \rangle$$

$$f_{ij} = 1 \quad (i=j)$$

$$= 0 \quad (i \neq j)$$

$$a_j \langle \hat{0} | \hat{0} \rangle = a_j^* \langle \hat{0} | \hat{0} \rangle$$

$$(a_j - a_j^*) f_{ij} = 0$$

$$i \text{ must} = j \text{ else } \rightarrow \emptyset$$

$$\therefore a_j = a_j^*$$

↑
real

I-4) ii) which of these ops is observable?

$$I^2, I_z, I_x, I_y$$

* use matrix (Pauli) & check transpose/cc

$$I^2 = \frac{3}{4} \hbar^2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad I^{2 \uparrow \uparrow} = \frac{3}{4} \hbar^2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \checkmark$$

$$I_z = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad I_z^{\uparrow \uparrow} = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \checkmark$$

$$I^+ = \hbar \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad I^+(\uparrow \uparrow) = \hbar \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad \text{No}$$

$$I_x = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad I_x^{\uparrow \uparrow} = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \checkmark$$

I-5) calculate

$$I^2 = \frac{3}{4} \hbar^2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad I^+ = \hbar \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$[I^2, I^+]$$

$$I_z = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad I_x = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

let $\hbar=1$

$$[I^2, I^+] = I^2 I^+ - I^+ I^2$$

$$= \frac{3}{4} \left[\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right]$$

$$= \frac{3}{4} \left[\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right] = 0$$

$$[I^2, I_x] = \frac{3}{4} \left[\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right]$$

$$= \frac{3}{4} \left[\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right] = 0$$

$$[I^2, I^+] = \frac{3}{4} \left[\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right]$$

$$= \frac{3}{4} \left[\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right] = 0$$

$$[I_z, I^+] = \frac{1}{2} \left[\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right]$$

$$= \frac{1}{2} \left[\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix} \right] = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = I^+$$

J-6) Show that
$$I^2 = I_z^2 + \frac{1}{2} (I_+ I_- + I_- I_+)$$

use
$$I_+ = I_x + i I_y \quad I_+ + I_- = 2I_x \quad I_+ - I_- = 2i I_y$$

$$I_- = I_x - i I_y \quad I_x = \frac{I_+ + I_-}{2} \quad I_y = \frac{I_+ - I_-}{2i}$$

$$I_+ I_+ = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad I_-^2 = I_z^2 + I_x^2 + I_y^2$$

$$I_x^2 = \frac{1}{4} [(I_+ + I_-)(I_+ + I_-)] = \frac{1}{4} [I_+ I_+ + I_+ I_- + I_- I_+ + I_- I_-]$$

$$I_y^2 = \frac{-1}{4} [(I_+ - I_-)(I_+ - I_-)] = \frac{-1}{4} [I_+ I_+ - I_+ I_- - I_- I_+ + I_- I_-]$$

$$= \frac{1}{4} [-I_+ I_+ + I_+ I_- + I_- I_+ - I_- I_-]$$

$$I_x^2 + I_y^2 = \frac{1}{4} [2I_+ I_- + 2I_- I_+] = \frac{I_+ I_- + I_- I_+}{2}$$

$$\therefore I^2 = I_z^2 + \frac{I_+ I_- + I_- I_+}{2}$$

I-7) Demonstrate that if 2 Hermitian ops A, B fulfill $[\hat{A}, \hat{B}] = 0$, then they possess a common basis of EFS (ie share same ψ_0)

$$\hat{A}\hat{B} - \hat{B}\hat{A} = 0$$

* see quantum notes prob set 4-4! somewhat of a logic question.

$$\hat{A}\psi_0 = a_0\psi_0$$

since $[\hat{A}, \hat{B}] = 0$

$$[\hat{A}, \hat{B}]\psi_0 = 0$$

$$\hat{A}\hat{B}\psi_0 = \hat{B}(\hat{A}\psi_0)$$

$$\hat{A}\hat{B}\psi_0 = a_0(\hat{B}\psi_0)$$

$$\hat{A}(\hat{B}\psi_0) = a_0(\hat{B}\psi_0)$$

using

$$\hat{A}\psi_0 = a_0\psi_0$$

we have $\hat{A}\hat{B}\psi_0 = a_0\hat{B}\psi_0$. we started with $\hat{A}\psi_0 = a_0\psi_0$.

EV The EF now

$\therefore \hat{B}\psi_0$ must be at most a constant $\times \psi_0$ (from $\hat{A}\psi_0 = a_0\psi_0$) Follow

ie) $B\psi_0 = c\psi_0$ } this is EV eqn for \hat{B} w/ EF ψ_0
Though

$\therefore [A, B]$ share same ψ_0

Hermitian ops 1) have real EV's

2) share same EF ψ

$$I-8) \quad \boxed{\hat{A} \psi_0 = a_0 \psi_0}$$

calc expectation value $\int \psi_0^* \hat{A} \psi_0 = a_0 \int \psi_0^* \psi_0$

(see standards Prob Set 1-5)

If \hat{A} is Hermitian $\left\{ \begin{array}{l} \text{substitute} \end{array} \right.$

can show this $\rightarrow \int \psi_j^* \hat{A} \psi_0 = \int (\hat{A} \psi_j)^* \psi_0$

using $\hat{A} \psi_0 = a_0 \psi_0$
 $\& \hat{B} \psi_j = a_j \psi_j$
 are seen here

substitute

$$\int (\hat{A} \psi_j)^* \psi_0 = a_0 \int \psi_j^* \psi_0$$

Use Hermitian identity too

$$\boxed{\text{now } \hat{A} \psi_j = a_j \psi_j}$$

$$\int (\hat{A} \psi_j)^* \psi_0 = \int (a_j \psi_j)^* \psi_0 = \int a_j^* \psi_j^* \psi_0$$

$$a_j^* = a_0 \quad \begin{array}{l} \text{real} \\ \downarrow \end{array}$$

$$\therefore a_j^* \int \psi_j^* \psi_0 = a_0 \int \psi_j^* \psi_0$$

\uparrow
 \therefore real

$$= (a_j^* - a_0) \int \psi_j^* \psi_0 = 0$$

$a_j^* = a_0 \left\{ \begin{array}{l} a_0 = \text{its complex} \\ \text{conj. i.e. real} \\ \text{i.e. no } i \text{ term} \end{array} \right.$

$$\Rightarrow = (a_j - a_0) \int \psi_j^* \psi_0 = 0$$

if $a_j \neq a_0$ Then $\int \psi_j^* \psi_0 \text{ must } = 0$ \therefore are orthogonal

$$\int \psi_j^* \psi_0 = \int \delta_{j0} \quad \begin{array}{l} \leftarrow \text{if } j=0 \rightarrow \\ \int \delta_{jj} = 1 \quad (j=0) \\ \int \delta_{j0} = 0 \quad (j \neq 0) \end{array}$$

	I_x	I_y	I_z	I^2	I^+	I^-
I_x	$\frac{I^2}{3}$	$\frac{i}{2} I_z$	$-\frac{i}{2} I_y$	$\frac{+3}{4} I_x$	$\frac{I^2}{3} - \frac{I_z}{2}$	$\frac{I^2}{3} + \frac{I_z}{2}$
I_y	$-\frac{i}{2} I_z$	$\frac{I^2}{3}$	$\frac{i}{2} I_x$	$\frac{3}{4} I_y$	$i\left(\frac{I^2}{3} - \frac{I_z}{2}\right)$	$i\left(\frac{I^2}{3} + \frac{I_z}{2}\right)$
I_z	$\frac{i}{2} I_y$	$-\frac{i}{2} I_x$	$\frac{I^2}{3}$	$\frac{3}{4} I_z$	$\frac{1}{2} I^+$	$-\frac{1}{2} I^-$
I^2	$\frac{3}{4} I_x$	$\frac{3}{4} I_y$	$\frac{3}{4} I_z$	$\frac{3}{4} I^2$	$\frac{3}{4} I^+$	$\frac{3}{4} I^-$
I^+	$\frac{I^2}{3} + \frac{I_z}{2}$	$i\left(\frac{I^2}{3} + \frac{I_z}{2}\right)$	$-\frac{1}{2} I^+$	$\frac{3}{4} I^+$	0	$\frac{2}{3} I^2 + I_z$
I^-	$\frac{I^2}{3} - \frac{I_z}{2}$	$i\left(\frac{I^2}{3} - \frac{I_z}{2}\right)$	$\frac{1}{2} I^-$	$\frac{3}{4} I^-$	$\frac{2}{3} I^2 - I_z$	0

above = R.C

let $\hbar=1$

$$I_z = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$I^+ = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$I^+ = I_x + i I_y$$

$$I^- = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$I^- = I_x - i I_y$$

$$I_x = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$I^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \frac{3}{4}$$

$$|a\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$I_y = \frac{+i}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$|b\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$[S_i, S_j] = i \epsilon_{ijk} S_k$$

$$\epsilon_{ijk} = \begin{cases} 1 & \text{if } ijk = xyz \\ -1 & \text{otherwise} \end{cases}$$

eg) $I_x I_y = i I_z$

I-9)

$$I_x I_x = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \frac{1}{4} I = \frac{\sqrt{2}}{3}$$

$$I^2 = \frac{1}{4} I$$

$$\frac{1}{3} I^2 = I$$

$$I_x I_y = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{1}{8} I_z$$

$$-I^2 = 1$$

$$I_x I_z = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \frac{1}{2} = \frac{1}{8} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \frac{1}{4} \frac{1}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$-I \cdot I = 1$$

$$= \frac{1}{4} \frac{-I}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$= -\frac{1}{4} I_y \checkmark$$

$$I_x I_z^2 = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \frac{3}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \frac{3}{16} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \frac{3}{4} I_x \checkmark$$

$$I_x I^4 = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \frac{1}{4} I^0$$

$$= \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \left[\frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \frac{1}{2} \right]$$

$$= \frac{1}{16} I + \frac{1}{8} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{1}{16} I + \frac{1}{4} \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$I_x I^4 = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \frac{1}{4} + \frac{1}{8} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \frac{1}{2}$$

$$= \frac{1}{16} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \frac{-1}{8} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\frac{1}{16} I - \frac{1}{4} \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{1}{16} I - \frac{1}{4} I_z \checkmark$$

$$I_x I_- = I_x I_x + I_x I_y$$

$$= \frac{11}{16} - \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \frac{1}{2} = -$$

$$-\frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \frac{11}{16} - \frac{1}{2} \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{11}{16} + \frac{I_2}{2}$$

$$I_x I_+ = I_x I_x + i I_x I_y$$

$$= \frac{11}{4} + i \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \frac{1}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \frac{11}{4} + (-1) \left(\frac{1}{4} \right) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$= \frac{11}{4} - \frac{1}{2} \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\frac{31}{4} = I^2$$

$$I = \frac{4I^2}{3}$$

$$= \frac{11}{4} - \frac{I_2}{2} = \frac{I^2}{3} - \frac{I_2}{2}$$

$I_x I_- =$ same as above sign change 2nd term

$$I_x I_- = \frac{I^2}{3} + \frac{I_2}{2}$$

$$I_x I^2 = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \frac{3}{4} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$I_y I_x = \frac{i}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 10 & 1 \end{pmatrix} = \frac{i}{4} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = \frac{-i}{2} \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = -\frac{I_z}{2}$$

$$I_y I_y = \frac{i}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \frac{i}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \frac{-1}{4} \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{1}{4} I = \frac{I^2}{3} \quad \text{and } I^2 = \frac{3}{4} I \dots$$

$$I^- I^+ = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{aligned} (I_x - i I_y)(I_x + i I_y) &= I_x I_x + i I_x I_y - i I_y I_x + I_y I_y \\ &= \frac{I^2}{3} + i \left(\frac{i I_z}{2} \right) - i \left(\frac{-i I_z}{2} \right) + \frac{I^2}{3} \\ &= \frac{I^2}{3} - \frac{I_z}{2} - \frac{I_z}{2} + \frac{I^2}{3} \\ &= \frac{2}{3} I^2 - I_z \end{aligned}$$

$$\begin{aligned} I^+ I^- &= (I_x + i I_y)(I_x - i I_y) \\ &= I_x I_x - i I_x I_y + i I_y I_x - i^2 I_y I_y \\ &= \frac{I^2}{3} - i \left(\frac{i I_z}{2} \right) + i \left(\frac{-i I_z}{2} \right) + \frac{I^2}{3} \\ &= \frac{2}{3} I^2 + \frac{I_z}{2} + \frac{I_z}{2} = \frac{2}{3} I^2 + I_z \end{aligned}$$

$$I-10) I_2 = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$I_2 | \alpha \rangle = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} | \alpha \rangle$$

$$I_2 | \beta \rangle = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 \\ -1 \end{pmatrix} = -\frac{1}{2} | \beta \rangle$$

$$\langle I_2 \rangle = \det \begin{vmatrix} \langle \alpha | I_2 | \alpha \rangle - \lambda & \langle \alpha | I_2 | \beta \rangle \\ \langle \beta | I_2 | \alpha \rangle & \langle \beta | I_2 | \beta \rangle - \lambda \end{vmatrix} = 0 \quad \begin{vmatrix} \frac{1}{2} - \lambda & 0 \\ 0 & -\frac{1}{2} - \lambda \end{vmatrix} = 0$$

$$\left(\frac{1}{2} - \lambda\right)\left(-\frac{1}{2} - \lambda\right) = 0 \quad \frac{-1}{4} + \frac{\lambda}{2} - \frac{\lambda}{2} + \lambda^2 = 0$$

$$\lambda^2 - \frac{1}{4} = 0 \quad \therefore \lambda = \pm \frac{1}{2}$$

$$\lambda = \frac{1}{2} \quad \begin{pmatrix} \frac{1}{2} - \frac{1}{2} & 0 \\ 0 & -\frac{1}{2} - \frac{1}{2} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \quad \begin{cases} -1c_2 = 0 \\ c_2 = 0 \therefore c_1 = 1 \end{cases}$$

Not sure about this $\odot \Rightarrow c_1^2 + 0^2 = 1 \quad \psi = | \alpha \rangle$

$$\lambda = -\frac{1}{2} \quad \begin{pmatrix} \frac{1}{2} - \left(-\frac{1}{2}\right) & 0 \\ 0 & -\frac{1}{2} - \left(-\frac{1}{2}\right) \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \quad \begin{cases} c_1 = 0 \\ c_2 = 1 \end{cases}$$

$$c_1^2 + c_2^2 = 1 \quad \psi = | \beta \rangle$$

could just note
it's a diag matrix
& read off EV &
EF

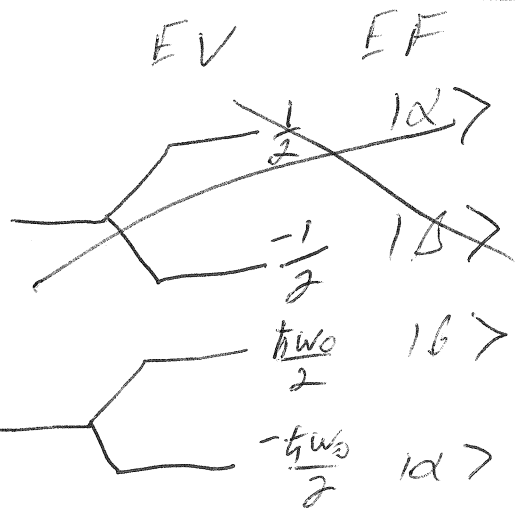
$$E = -\mu \cdot B$$

$$M = \gamma \hbar I_2 B$$

$$\langle \alpha | \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} | \alpha \rangle$$

So
Flips

$E \uparrow$



$$\Delta E = \hbar \omega = h \nu$$

$$I-10) \quad I_x = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$I_x |\alpha\rangle = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} |\beta\rangle$$

$$I_x |\beta\rangle = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} |\alpha\rangle$$

$$\langle I_x \rangle = \det \begin{vmatrix} \langle \alpha | I_x | \alpha \rangle - \lambda & \langle \alpha | I_x | \beta \rangle \\ \langle \beta | I_x | \alpha \rangle & \langle \beta | I_x | \beta \rangle - \lambda \end{vmatrix} = \begin{vmatrix} -\lambda & \frac{1}{2} \\ \frac{1}{2} & -\lambda \end{vmatrix} = 0$$

$$\lambda^2 - \frac{1}{4} = 0 \quad \therefore \lambda = \pm \frac{1}{2} \quad \text{eigenvalues}$$

$$\lambda = \frac{1}{2} \quad \begin{pmatrix} -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \begin{cases} -\frac{c_1}{2} + \frac{c_2}{2} = 0 \\ \frac{c_1}{2} - \frac{c_2}{2} = 0 \end{cases} \quad \begin{aligned} \frac{c_1}{2} &= \frac{c_2}{2} \\ c_1 &= c_2 \end{aligned}$$

$$\therefore c_1^2 + c_2^2 = 1 \quad \text{and } c_1^2 = 1 \quad c_1 = \frac{1}{\sqrt{2}} \quad \therefore c_2 = \frac{1}{\sqrt{2}}$$

$$\Psi = \frac{1}{\sqrt{2}} (|\alpha\rangle + |\beta\rangle)$$

$|e_1\rangle = (c, c)$ form all EFS
"actual" w EV = 1/2

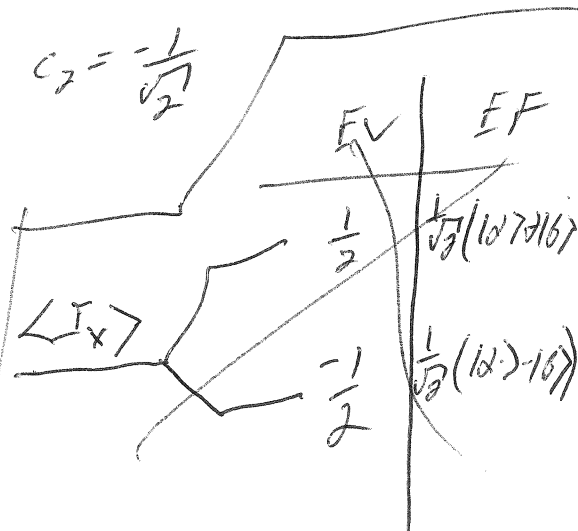
$$\lambda = -\frac{1}{2} \quad \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \begin{cases} \frac{c_1}{2} + \frac{c_2}{2} = 0 \\ \frac{c_1}{2} + \frac{c_2}{2} = 0 \end{cases} \quad c_1 = -c_2$$

$$c_1^2 + (-c_2)^2 = 1 \quad c_1 = \frac{1}{\sqrt{2}} \quad c_2 = -\frac{1}{\sqrt{2}}$$

$$\therefore \Psi = \frac{1}{\sqrt{2}} (|\alpha\rangle - |\beta\rangle)$$

$$= \frac{1}{\sqrt{2}} (|\beta\rangle - |\alpha\rangle)$$

$E = -\frac{1}{2}$ in EFS
"actual"
 \nearrow not



$$I-10) \quad I_y = \frac{\hbar}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \quad I_y |\alpha\rangle = \frac{\hbar}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{\hbar}{2} |\beta\rangle$$

$$I_y |\beta\rangle = \frac{\hbar}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} -1 \\ 0 \end{pmatrix} = -\frac{\hbar}{2} |\alpha\rangle$$

$$\langle I_y \rangle = \det \begin{vmatrix} \langle \alpha | I_y | \alpha \rangle - \lambda & \langle \alpha | I_y | \beta \rangle \\ \langle \beta | I_y | \alpha \rangle & \langle \beta | I_y | \beta \rangle - \lambda \end{vmatrix} = 0 \quad \begin{vmatrix} 0 - \lambda & \frac{\hbar}{2} \\ \frac{\hbar}{2} & 0 - \lambda \end{vmatrix} = 0$$

$$\det \begin{vmatrix} -\lambda & \frac{\hbar}{2} \\ \frac{\hbar}{2} & -\lambda \end{vmatrix} = 0 \quad \lambda^2 = \left(\frac{\hbar}{2}\right)\left(\frac{\hbar}{2}\right) \Rightarrow \lambda^2 = \left(\frac{\hbar^2}{4}\right) \\ = \lambda^2 = \frac{1}{4} \quad \therefore \lambda = \pm \frac{1}{2}$$

$$\lambda = \frac{1}{2} \quad \begin{pmatrix} \frac{\hbar}{2} & \frac{\hbar}{2} \\ \frac{\hbar}{2} & -\frac{\hbar}{2} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \begin{cases} -\frac{c_1}{2} + \frac{c_2}{2} = 0 \\ \frac{c_1}{2} - \frac{c_2}{2} = 0 \end{cases} \quad \therefore c_1 = c_2 \quad \begin{cases} c_1 = c_2 \\ \text{are EFS} \\ \omega/EV = \frac{1}{2} \end{cases}$$

$$c_1 = \frac{1}{\sqrt{2}} \quad \text{Just use } c_1 = c_2 \quad \therefore c_1 = \frac{1}{\sqrt{2}} \text{ \& } c_2 = \frac{1}{\sqrt{2}} \\ c_2 = -1 \quad \text{thru } c_1^2 + c_2^2 = 1$$

$$\Psi = \frac{1}{\sqrt{2}} (|\alpha\rangle + |\beta\rangle)$$

$$\lambda = -\frac{1}{2} \quad \begin{pmatrix} \frac{\hbar}{2} & \frac{\hbar}{2} \\ \frac{\hbar}{2} & -\frac{\hbar}{2} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \begin{cases} \frac{c_1}{2} + \frac{c_2}{2} = 0 \\ \frac{c_1}{2} - \frac{c_2}{2} = 0 \end{cases} \quad \therefore c_1 = -c_2 \\ \text{Just use } c_1 = -c_2 \text{ for Normalization}$$

$$\therefore c_1^2 + c_2^2 = 1 \Rightarrow c_1 = \frac{1}{\sqrt{2}} \text{ \& } c_2 = -\frac{1}{\sqrt{2}}$$

$$\Psi = \frac{1}{\sqrt{2}} (|\alpha\rangle - |\beta\rangle)$$

$$E = -M_2 \cdot B_0$$

$$E \begin{cases} \frac{\hbar\omega}{2} & \frac{1}{\sqrt{2}} (|\alpha\rangle - |\beta\rangle) \\ -\frac{\hbar\omega}{2} & \frac{1}{\sqrt{2}} (|\alpha\rangle + |\beta\rangle) \end{cases}$$

$$\lambda = \frac{1}{2} \begin{pmatrix} -\frac{1}{2} & \frac{\sigma}{2} \\ \frac{\sigma}{2} & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \begin{cases} -\frac{c_1}{2} + \frac{\sigma c_2}{2} = 0 \\ c_1 = \sigma c_2 \end{cases}$$

$$c_1^2 + c_2^2 = 1$$

$$(\sigma c_2)^2 + c_2^2 = 1$$

∴ vectors $e_i = (c, \sigma c)$ form an orthonormal basis
w/ef = $\frac{1}{2}$

eg) $(1, 0)$ (σ, σ)

$$\Psi = (\sigma | \uparrow + | \downarrow) \frac{1}{\sqrt{2}}$$

$$\lambda = -\frac{1}{2} \begin{pmatrix} \frac{1}{2} & \frac{\sigma}{2} \\ \frac{\sigma}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \begin{cases} \frac{c_1}{2} + \frac{\sigma c_2}{2} = 0 \\ c_1 = -\sigma c_2 \end{cases}$$

Just use
 $c_1 = -c_2$

vectors of form $e_i = (c, -\sigma c)$ are
ef's w/ef = $-\frac{1}{2}$

$$\Psi = (\sigma | \downarrow - | \uparrow) \frac{1}{\sqrt{2}}$$

$$E \begin{cases} \frac{\hbar \omega_0}{2} (\sigma | \downarrow - | \uparrow) \\ -\frac{\hbar \omega_0}{2} (\sigma | \uparrow + | \downarrow) \end{cases}$$

$$E = -M_z B_0$$

$$I_{x10} \begin{matrix} \alpha\alpha & \alpha\beta \\ \beta\alpha & \beta\beta \end{matrix}$$

$$I_x |\alpha\rangle = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} |\beta\rangle$$

$$I_x |\beta\rangle = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} |\alpha\rangle$$

$$\begin{pmatrix} \langle \alpha | I_x | \alpha \rangle - \lambda & \langle \alpha | I_x | \beta \rangle \\ \langle \beta | I_x | \alpha \rangle & \langle \beta | I_x | \beta \rangle - \lambda \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = 0$$

$$\begin{pmatrix} \frac{1}{2} \langle \alpha | \beta \rangle - \lambda & \frac{1}{2} \langle \alpha | \alpha \rangle \\ \frac{1}{2} \langle \beta | \beta \rangle & \frac{1}{2} \langle \beta | \alpha \rangle - \lambda \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = 0 \quad \begin{pmatrix} 0 & \frac{1}{2} \\ \frac{1}{2} & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = 0$$

$$\frac{1}{2} c_2 + \frac{1}{2} c_1 = 0 \quad c_1 = -c_2 \quad c_1^2 + c_2^2 = 1$$

$$c_1 = \frac{1}{\sqrt{2}} \quad c_2 = -\frac{1}{\sqrt{2}}$$

$$EVS = \langle I_x \rangle = \frac{1}{2} = \lambda$$

$$\psi = \frac{1}{\sqrt{2}} (|\alpha\rangle - |\beta\rangle) \text{ or } \frac{1}{\sqrt{2}} (|\beta\rangle - |\alpha\rangle)$$

$$\langle I_y \rangle \Rightarrow \begin{pmatrix} \langle \alpha | I_y | \alpha \rangle & \langle \alpha | I_y | \beta \rangle \\ \langle \beta | I_y | \alpha \rangle & \langle \beta | I_y | \beta \rangle \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = 0$$

$$I_y |\alpha\rangle = \frac{i}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{-i}{2} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{-i}{2} |\beta\rangle$$

$$I_y |\beta\rangle = \frac{i}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{i}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{i}{2} |\alpha\rangle$$

$$\begin{pmatrix} 0 & -i/2 \\ -i/2 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = 0$$

$$c_1^2 + c_2^2 = 0 \Rightarrow c_1 = \frac{1}{\sqrt{2}}$$

$$c_2 = -\frac{1}{\sqrt{2}}$$

$$-\frac{i}{2} c_1 - \frac{i}{2} c_2 = 0 \quad c_1 = -c_2$$

$$\langle I_y \rangle = \frac{-i}{2}$$

$$\psi = \frac{1}{\sqrt{2}} (|\alpha\rangle - |\beta\rangle) \text{ or } \frac{1}{\sqrt{2}} (|\beta\rangle - |\alpha\rangle)$$

I-11) The e.s of $S=1$ are: $I_z |+1\rangle = \hbar |+1\rangle$

$$I_z |0\rangle = 0$$

$$I_z |-1\rangle = -\hbar |-1\rangle$$

use: $I_+ |+1\rangle = 0$

$$I_- |+1\rangle = \sqrt{2} |0\rangle$$

$$I_+ |0\rangle = \sqrt{2} |+1\rangle$$

$$I_- |0\rangle = \sqrt{2} |-1\rangle$$

$$I_+ |-1\rangle = \sqrt{2} |0\rangle$$

$$I_- |-1\rangle = 0$$

Calculate I_x, I_y, I_z, I^2 in matrix form $\langle I_x \rangle = \langle \rangle \langle \rangle$

$$\begin{matrix} \langle +1 | \\ \langle 0 | \\ \langle -1 | \end{matrix} \begin{pmatrix} |1\rangle & |0\rangle & |-1\rangle \\ \langle 1 | I_x | 1 \rangle & \langle 1 | I_x | 0 \rangle & \langle 1 | I_x | -1 \rangle \\ \langle 0 | I_x | 1 \rangle & \langle 0 | I_x | 0 \rangle & \langle 0 | I_x | -1 \rangle \\ \langle -1 | I_x | 1 \rangle & \langle -1 | I_x | 0 \rangle & \langle -1 | I_x | -1 \rangle \end{pmatrix} = \langle I_x \rangle$$

etc.

$I = 1 \oplus$

$$J_z = \begin{matrix} & 1 & 0 & -1 \\ 1 & \langle 1|I_z|1\rangle & \langle 1|I_z|0\rangle & \langle 1|I_z|-1\rangle \\ 0 & \langle 0|I_z|1\rangle & \langle 0|I_z|0\rangle & \langle 0|I_z|-1\rangle \\ -1 & \langle -1|I_z|1\rangle & \langle -1|I_z|0\rangle & \langle -1|I_z|-1\rangle \end{matrix}$$

$$\begin{aligned} I_z|1\rangle &= \hbar|1\rangle \\ I_z|0\rangle &= 0 \\ I_z|-1\rangle &= -\hbar|-1\rangle \end{aligned}$$

$$\langle I_z \rangle = \begin{pmatrix} \hbar & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\hbar \end{pmatrix} = \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$J^2 = J_x^2 + J_y^2 + J_z^2$$

~~$$J_x^2 = \frac{1}{2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = 0 \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + 1 \cdot \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$~~

See other page

$$I_{\pm} = I_x + i I_y, \quad |I_x| \therefore I_x = \frac{I_+ + I_-}{2} \quad I_y = \frac{I_+ - I_-}{2i}$$

$$I_- = I_x - i I_y$$

$$\langle I_x | 1 \rangle = \frac{\langle I_+ | 1 \rangle + \langle I_- | 1 \rangle}{2} = \frac{\sqrt{2} \langle 1 | 0 \rangle + \langle 1 | 1 \rangle}{2} = \frac{1 \langle 1 | 0 \rangle + \langle 1 | 1 \rangle}{\sqrt{2}}$$

$$\langle I_x | 0 \rangle = \frac{\langle I_+ | 0 \rangle + \langle I_- | 0 \rangle}{2} = \frac{\sqrt{2} \langle 0 | 1 \rangle + \sqrt{2} \langle 0 | -1 \rangle}{2} = \frac{\sqrt{2} (\langle 0 | 1 \rangle + \langle 0 | -1 \rangle)}{2}$$

$$\langle I_x | -1 \rangle = \frac{1}{\sqrt{2}} (\langle I_+ | -1 \rangle + \langle I_- | -1 \rangle) = \frac{\sqrt{2} \langle 0 | 0 \rangle + \langle -1 | -1 \rangle}{2} = \frac{1 \langle -1 | -1 \rangle}{2}$$

Note $\langle 1 | 0 \rangle = 0$ etc

$$\langle 1 | -1 \rangle = 0$$

$$\langle 1 | 1 \rangle = 1$$

$$\begin{pmatrix} \langle 1 | 0 \rangle / \sqrt{2} & \left(\frac{\langle 1 | 1 \rangle}{\sqrt{2}} + \frac{\langle 1 | -1 \rangle}{\sqrt{2}} \right) & \frac{\langle 1 | 0 \rangle}{\sqrt{2}} \\ \langle 0 | 0 \rangle / \sqrt{2} & \left(\frac{\langle 0 | 1 \rangle}{\sqrt{2}} + \frac{\langle 0 | -1 \rangle}{\sqrt{2}} \right) & \frac{\langle 0 | 0 \rangle}{\sqrt{2}} \\ \langle -1 | 0 \rangle / \sqrt{2} & \left(\frac{\langle -1 | 1 \rangle}{\sqrt{2}} + \frac{\langle -1 | -1 \rangle}{\sqrt{2}} \right) & \frac{\langle -1 | 0 \rangle}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & 0 \end{pmatrix}$$

$$\langle I_x \rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

I_{-11} $I_{+11} - I_{-11} / 2e$
 $I_y \Rightarrow$ ~~I_{+11}~~ ~~I_{-11}~~

$$I_y | 11 \rangle = \frac{I_{+11} | 11 \rangle - I_{-11} | 11 \rangle}{2e} = \left(\frac{-\sqrt{2} | 10 \rangle}{2e} - \frac{(-1) | 0 \rangle}{\sqrt{2} e} \right)$$

$$I_y | 10 \rangle = \frac{I_{+10} | 10 \rangle - I_{-10} | 10 \rangle}{2e} = \left(\frac{\sqrt{2} | 11 \rangle - \sqrt{2} | 1 \bar{1} \rangle}{2e} \right) = \left(\frac{| 11 \rangle - | 1 \bar{1} \rangle}{\sqrt{2} e} \right)$$

$$I_y | 1 \bar{1} \rangle = \frac{I_{+1 \bar{1}} | 1 \bar{1} \rangle - I_{-1 \bar{1}} | 1 \bar{1} \rangle}{2e} = \frac{\sqrt{2} | 10 \rangle}{2e} = \frac{| 10 \rangle}{\sqrt{2} e}$$

$$\begin{pmatrix} \langle 11 | I_y | 11 \rangle & \langle 11 | I_y | 10 \rangle & \langle 11 | I_y | 1 \bar{1} \rangle \\ \langle 01 | I_y | 11 \rangle & \langle 01 | I_y | 10 \rangle & \langle 01 | I_y | 1 \bar{1} \rangle \\ \langle -1 | I_y | 11 \rangle & \langle -1 | I_y | 10 \rangle & \langle -1 | I_y | 1 \bar{1} \rangle \end{pmatrix} = \frac{1}{\sqrt{2} e} \begin{pmatrix} -\langle 11 | 10 \rangle & (\langle 11 | 11 \rangle - \langle 11 | \bar{1} \bar{1} \rangle) & \langle 11 | 0 \rangle \\ -\langle 01 | 10 \rangle & \langle 01 | 11 \rangle - \langle 01 | \bar{1} \bar{1} \rangle & \langle 01 | 0 \rangle \\ -\langle -1 | 10 \rangle & \langle -1 | 11 \rangle - \langle -1 | \bar{1} \bar{1} \rangle & \langle -1 | 0 \rangle \end{pmatrix}$$

~~$$\frac{\langle 11 | 0 \rangle}{\sqrt{2} e} \quad \frac{(\langle 11 | 11 \rangle - \langle 11 | \bar{1} \bar{1} \rangle)}{\sqrt{2} e} \quad \frac{\langle 11 | 0 \rangle}{\sqrt{2} e}$$~~

~~$$\frac{\langle 01 | 11 \rangle - \langle 01 | \bar{1} \bar{1} \rangle}{\sqrt{2} e} \quad \langle 01 | 0 \rangle$$~~

$$= \frac{1}{\sqrt{2} e} \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$\langle I_y \rangle = \frac{1}{\sqrt{2} e} \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} = \frac{e}{\sqrt{2}} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$I-11) \quad I^2 = I_x^2 + I_y^2 + I_z^2$$

$$I_x^2 = \frac{1}{2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 1 \end{pmatrix} \frac{1}{2}$$

$$I_y^2 = \frac{-1}{2} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & -1 \end{pmatrix} \frac{-1}{2} = \frac{1}{2} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

$$I_z^2 = \hbar^2 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \hbar^2$$

$$I_x^2 + I_y^2 = \frac{1}{2} \left[\begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 1 \end{pmatrix} + \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix} \right] = \frac{1}{2} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 2 \end{bmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$I_z^2 + (I_x^2 + I_y^2) = \hbar^2 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \hbar^2 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$I_z^2 + I_x^2 + I_y^2 = \hbar^2 \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix} = 2\hbar^2 \mathbb{1}$$

I-12) generalize the expressions $\langle M_{x,y,z}(t) \rangle$ for $S=1$
 (Hilbert space here)

$\langle M_x(t) \rangle = \gamma \hbar S_z \neq$ $S_z = \begin{pmatrix} 11 & 10 & 1-1 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$

note

$I_z |1\rangle = \hbar$
 $I_z |0\rangle = 0$
 $I_z |-1\rangle = -\hbar$

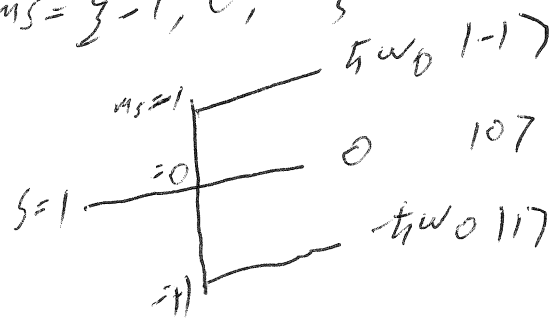
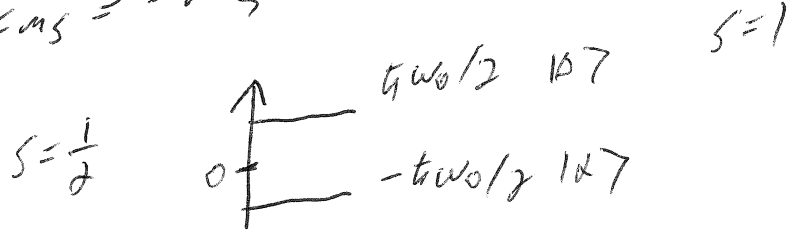
$|\psi(t)\rangle = a_1^0 |1\rangle + a_0^0 |0\rangle + a_{-1}^0 |-1\rangle$

$m_s = \{ -S, \dots, S \}$

$E = -\vec{\mu} \cdot \vec{B}_0 = -S_z \hbar \gamma B_0 = -m_s \hbar \gamma B_0$

$m_s = \{ -1, 0, 1 \}$

$E_{m_s} = -m_s \hbar \omega_0$



$S = \frac{1}{2} \quad \begin{pmatrix} -1/2 & 1/2 \\ 1/2 & 1/2 \end{pmatrix}$

$|\psi(t)\rangle = a_1 |1\rangle + a_0 |0\rangle + a_{-1} |-1\rangle$

$a_1 = a e^{i\alpha}$
 $a_0 = b e^{i\beta}$
 $a_{-1} = c e^{i\gamma}$

$= a e^{i\alpha} |1\rangle + b e^{i\beta} |0\rangle + c e^{i\gamma} |-1\rangle$

Note: $c_j(t) = c_j^0 e^{-i \left(\frac{E_j}{\hbar} \right) t} = c_j^0 e^{-i \omega_j t}$

$\frac{E_j}{\hbar} = \omega_j = \text{Bohr Frequency}$

$= c_j^0 e^{i(-\omega_j t)}$

$$c_2(t) = c_2^0 e^{-i\omega_0 t} = c_2^0 e^{i(-\omega_0 t)}$$

$$\therefore |\psi(t)\rangle = d_0 e^{i(+\omega_0 t + \alpha)} |1\rangle + b_0 e^{i\beta} |0\rangle + g_0 e^{i(-\omega_0 t + \gamma)} |-1\rangle$$

$(S=1)$ time dep wave func (as defined by \hbar)

Let $A = \omega_0 t + \alpha$ $B = \beta$ $C = -\omega_0 t + \gamma$

$$|\psi(t)\rangle = d_0 e^{iA} |1\rangle + b_0 e^{iB} |0\rangle + g_0 e^{iC} |-1\rangle$$

$$|\psi(t)\rangle = d_0 e^{iA} |1\rangle + b_0 e^{iB} |0\rangle + g_0 e^{iC} |-1\rangle$$

$$\langle M \rangle = \hbar \langle I_x \rangle$$

note $S=1 \Rightarrow I_z = \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$

$$I_x = \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$I_y = \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

From previous problem I-11

We have everything now $|\psi(t)\rangle \neq \langle I_3 \rangle$ SPIN=1

$$\langle S_z \rangle = \gamma \hbar \langle I_z \rangle \Rightarrow$$

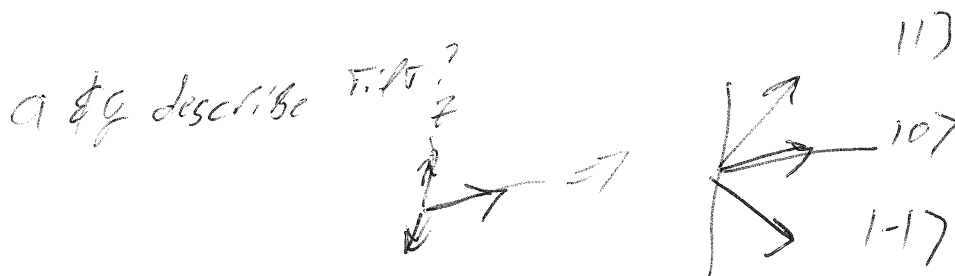
$$\gamma \hbar \begin{pmatrix} a_0 e^{-iA} & b e^{-iB} & g e^{-iC} \\ a_0 e^{iA} & b e^{iB} & g e^{iC} \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} a e^{iA} \\ b e^{iB} \\ g e^{iC} \end{pmatrix}$$

$$= \begin{pmatrix} -iA & -iB & -iC \\ a e^{iA} & b e^{iB} & g e^{iC} \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} a e^{iA} \\ 0 \\ -g e^{iC} \end{pmatrix} = \begin{pmatrix} -iA & iA & -iC & iC \\ a e^{iA} \cdot a e^{iA} & -g e^{iC} & g e^{iC} & \end{pmatrix}$$

$$= (a^2 - g^2) \gamma \hbar^2$$

$\langle S_z \rangle = \gamma \hbar^2 (a^2 - g^2)$

 $= \cancel{\gamma \hbar^2 (a_1^2 - a_{-1}^2)} = \gamma \hbar^2 (a_1^2 - a_{-1}^2)$



$$\langle S_x \rangle = \gamma \hbar \langle I_x \rangle = \frac{\gamma \hbar}{\sqrt{2}} \begin{pmatrix} a_0 e^{-iA} & b e^{-iB} & c e^{-iC} \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} a e^{+iA} \\ b e^{+iB} \\ g e^{+iC} \end{pmatrix}$$

$$= \begin{pmatrix} a e^{-iA} & b e^{-iB} & g e^{-iC} \end{pmatrix} \begin{pmatrix} b e^{+iB} \\ a e^{+iA} + g e^{+iC} \\ b e^{+iA} \end{pmatrix}$$

$$= a e^{-iA} b e^{+iB} + b e^{-iB} (a e^{+iA} + g e^{+iC}) + g e^{-iC} b e^{+iA}$$

$$= a b e^{-iA} e^{+iB} + a b e^{+i(A-B)} + b g e^{+i(B-C)} + b g e^{+i(B-A)}$$

$$= a b \left(e^{-i(A-B)} + e^{+i(A-B)} \right) + b g \left(e^{-i(B-C)} + e^{+i(B-C)} \right)$$

$$= a b \left[2 \cos(A-B) \right] + b g \left[2 \cos(B-C) \right]$$

$$= a b [2 \cos(A-B)] + b g [2 \cos(B-C)]$$

$$a_1 \Rightarrow A = \omega t + \alpha$$

$$a_0 \Rightarrow B = \beta$$

$$a_{-1} \Rightarrow C = -\omega t + \gamma$$

$$A-B = \omega t + (\alpha - \beta)$$

$$B-C = \beta - (-\omega t + \gamma) = \omega t + (\beta - \gamma)$$

$$\Phi = \alpha - \beta$$

$$\Delta = \beta - \gamma$$

$$\langle S_x \rangle = \frac{\gamma \hbar}{\sqrt{2}} \left[2 \cos(\omega t + \alpha - \beta) \right] + \frac{\gamma \hbar}{\sqrt{2}} \left[2 \cos(\omega t + \beta - \gamma) \right]$$

$$\langle S_x \rangle = \sqrt{2} \gamma \hbar a_1 a_0 \cos(\omega t + \alpha - \beta) + \sqrt{2} \gamma \hbar a_0 a_{-1} \cos(\omega t + \beta - \gamma)$$

$$\langle M_y \rangle = \gamma \hbar \langle S_y \rangle$$

$$S_y = \frac{\hbar}{2} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\langle M_y \rangle = \frac{\gamma \hbar}{\sqrt{2}} \begin{pmatrix} a e^{-iA} & b e^{-iB} & g e^{-i\phi} \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} a e^{iA} \\ b e^{iB} \\ g e^{i\phi} \end{pmatrix}$$

$$= \frac{\gamma \hbar}{\sqrt{2}} \begin{pmatrix} a e^{-iA} & b e^{-iB} & g e^{-i\phi} \\ -b e^{iB} & a e^{iA} - g e^{i\phi} \\ b e^{iB} \end{pmatrix}$$

$$= \frac{\gamma \hbar}{\sqrt{2}} \left[-ab e^{-iA} e^{iB} + b e^{-iB} (a e^{iA} - g e^{i\phi}) + b g e^{-i\phi} e^{iB} \right]$$

$$= \frac{\gamma \hbar}{\sqrt{2}} \left[-ab e^{i(B-A)} + ab e^{i(A-B)} - b g e^{i(B-\phi)} + b g e^{i(\phi-B)} \right]$$

$$= \frac{\gamma \hbar}{\sqrt{2}} \left[ab (-e^{i(A-B)} + e^{i(B-A)}) + b g (e^{i(\phi-B)} - e^{i(B-\phi)}) \right]$$

$$= \frac{\gamma \hbar}{\sqrt{2}} \left[ab \begin{bmatrix} -\cos(A-B) + i \sin(A-B) \\ \cos(A-B) + i \sin(A-B) \end{bmatrix} + b g \begin{bmatrix} \cos(\phi-B) + i \sin(\phi-B) \\ -\cos(\phi-B) + i \sin(\phi-B) \end{bmatrix} \right]$$

$$= \frac{\gamma \hbar}{\sqrt{2}} \left[ab 2i \sin(A-B) + b g 2i \sin(\phi-B) \right]$$

$$= -\gamma \hbar \sqrt{2} \left[ab \sin(\omega t + \alpha - B) + b g \sin(\omega t + \beta - \gamma) \right]$$

$$\langle M_y(t) \rangle = -\gamma \hbar \sqrt{2} \left[a_1 a_0 \sin(\omega t + \alpha - B) + a_0 a_{-1} \sin(\omega t + \beta - \gamma) \right]$$

↑
 2 terms added in sin func w/ coeffs w/ increments
 5

J-12) Review:

$$H = -\vec{\mu} \cdot \vec{B}$$

$$M = \gamma \vec{S} \quad \vec{B} = B_0 \hat{z}$$

$$H = -\gamma B_0 S_z$$

H1

$$H = \sum \{ |2\rangle, |B\rangle \} \left. \begin{array}{l} E \\ \uparrow \\ |A\rangle \end{array} \right\} \begin{array}{l} 1B7 \\ \hline \frac{\hbar \omega_0}{2} \\ \hline -\frac{\hbar \omega_0}{2} \end{array}$$

$$\Delta E = \hbar \omega_0 = h \nu$$

Rabi Frequency describes time evolution of the spin

Initially $|\psi\rangle = a_{1/2} |2\rangle + a_{-1/2} |B\rangle$

$$a_{1/2}^0 = a e^{i\alpha}$$

$$a_{-1/2}^0 = b e^{i\beta}$$

The Phases

$$\text{where } a^2 + b^2 = 1$$

$$a, b \in \mathbb{R} \quad (\text{just real}) > 0$$

a & b are scalars describing how much a & b in ψ

$$\Rightarrow |\psi(t)\rangle = a e^{i(\frac{\omega_0 t}{2} + \alpha)} |2\rangle + b e^{i(-\frac{\omega_0 t}{2} + \beta)} |B\rangle$$

With $|\psi(t)\rangle$ we can now evaluate the time dependence of

The magnetization

$$\langle \vec{M} \rangle = \gamma \hbar \begin{pmatrix} \langle S_x \rangle \\ \langle S_y \rangle \\ \langle S_z \rangle \end{pmatrix}$$

$$N = \# \text{ of spin pairs} = 2 \text{ (for 2 } a \& b \text{)}$$

$$\langle M_x(t) \rangle = ab N \cos(\omega_0 t + \phi) \cdot (\gamma \hbar)$$

$$\langle M_y(t) \rangle = -ab N \sin(\omega_0 t + \phi) \cdot (\gamma \hbar)$$

$$\langle M_z(t) \rangle = N(a^2 - b^2) \left(\frac{\gamma \hbar}{2} \right)$$

gives magnetic moments for a particular particle

$$\langle M_x(t) \rangle = \gamma \hbar \langle S_x \rangle \quad S_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$|\psi(t)\rangle = a e^{i(\frac{\omega_0 t}{2} + \alpha)} | \alpha \rangle + b e^{i(-\frac{\omega_0 t}{2} + \beta)} | \beta \rangle$$

$$\text{let } A = \frac{\omega_0 t}{2} + \alpha \quad \& \quad B = -\frac{\omega_0 t}{2} + \beta$$

$$|\psi(t)\rangle = a e^{iA} | \alpha \rangle + b e^{iB} | \beta \rangle$$

$$\langle M_x(t) \rangle = \langle \psi(t) | S_x | \psi(t) \rangle \gamma \hbar$$

$$= (a e^{-iA} + b e^{-iB}) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a e^{iA} \\ b e^{iB} \end{pmatrix} \gamma \hbar$$

$$= (a e^{-iA} + b e^{-iB}) \begin{pmatrix} b e^{iB} \\ a e^{iA} \end{pmatrix} \gamma \hbar = (a b e^{-iA} e^{iB} + a b e^{-iB} e^{iA}) \gamma \hbar$$

$$= \gamma \hbar a b \left[e^{i(A-B)} + e^{i(B-A)} \right]$$

$$A-B = \frac{\omega_0 t}{2} + \alpha - (-\frac{\omega_0 t}{2} + \beta) = \frac{\omega_0 t}{2} + \phi$$

$$B-A = -\frac{\omega_0 t}{2} + \beta - \frac{\omega_0 t}{2} - \alpha = -\frac{\omega_0 t}{2} - \phi \quad \phi = \alpha - \beta$$

$$\langle M_x(t) \rangle = \gamma \hbar a b \left[e^{i u} + e^{-i u} \right]$$

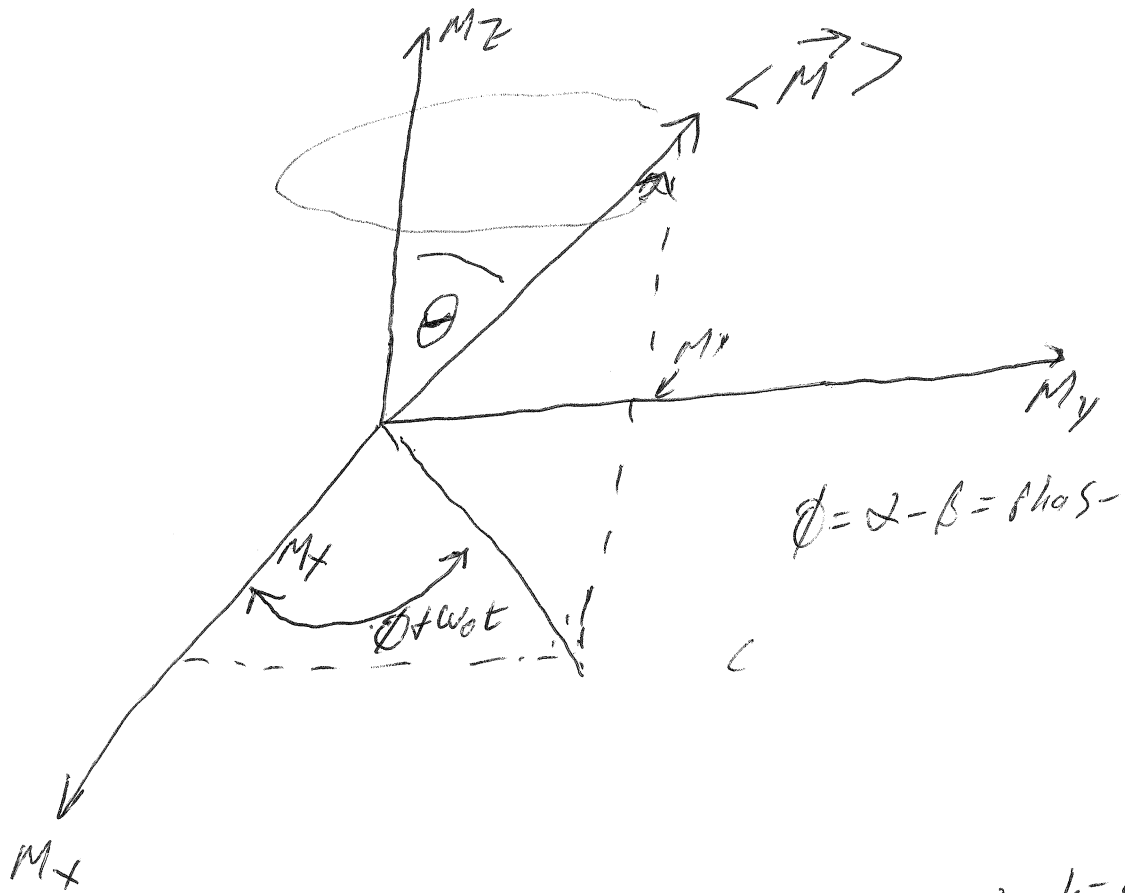
Let $u = \frac{\omega_0 t}{2} + \phi$

$$= \gamma \hbar a b \left[e^{i u} + e^{-i u} \right] = \gamma \hbar a b \left[\cos(u) + i \sin(u) + \cos(u) - i \sin(u) \right]$$

$$= \gamma \hbar a b \left[2 \cos\left(\frac{\omega_0 t}{2} + \phi\right) \right]$$

$$\langle M_x(t) \rangle = 2 a b \gamma \hbar \cos(\omega_0 t + \phi) \quad \langle M_x(t) \rangle = 2 a b \gamma \hbar \cos(\omega_0 t + \phi)$$

OUR VECTOR SPACE



$$\phi = \alpha - \beta$$

$$\cos(\theta) = 2a^2 - 1 = \begin{cases} 1 \rightarrow a=1, b=0 \\ 0 \rightarrow a=b=\frac{1}{2} \\ -1 \rightarrow a=0, b=1 \end{cases}$$

$a^2 + b^2 = 1$ remember \rightarrow

Find the so:
$$\Psi(t) = \cos\left(\frac{\theta}{2}\right) e^{i\left(\frac{\phi}{2} + \omega_0 t\right)} |\alpha\rangle + \sin\left(\frac{\theta}{2}\right) e^{-i\left(\frac{\phi}{2} + \omega_0 t\right)} |\beta\rangle$$

$$\langle M_z(t) \rangle = \gamma \hbar \langle S_z \rangle \quad I_z = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$|\psi(t)\rangle = a e^{i(\frac{\omega_0 t}{2} + \alpha)} |a\rangle + b e^{i(-\frac{\omega_0 t}{2} + \beta)} |b\rangle$$

$$\text{Let } A = \frac{\omega_0 t}{2} + \alpha \quad \& \quad B = -\frac{\omega_0 t}{2} + \beta$$

$$|\psi(t)\rangle = a e^{iA} |a\rangle + b e^{iB} |b\rangle$$

$$\langle M_z(t) \rangle = \frac{\gamma \hbar}{2} \begin{pmatrix} a e^{-iA} & b e^{-iB} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} a e^{iA} \\ b e^{iB} \end{pmatrix}$$

$$= \frac{\gamma \hbar}{2} \begin{pmatrix} a e^{-iA} & b e^{-iB} \end{pmatrix} \begin{pmatrix} a e^{iA} \\ -b e^{iB} \end{pmatrix}$$

$$= \frac{\gamma \hbar}{2} [a^2 e^{-iA} e^{iA} - b^2 e^{-iB} e^{iB}]$$

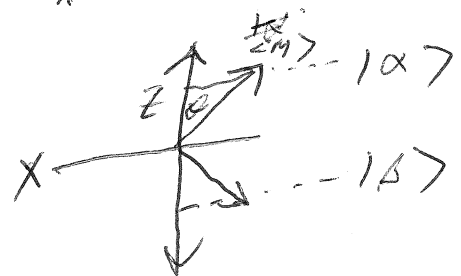
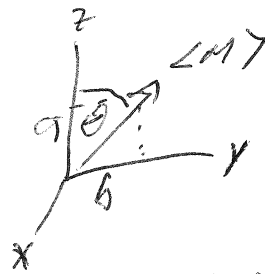
$$\therefore \langle M_z(t) \rangle = \frac{\gamma \hbar}{2} [a^2 - b^2]$$

$$a^2 + b^2 = 1$$

$$\langle I_z \rangle = \langle M_z \rangle$$

$$\langle I_z \rangle = 2a^2 - 1$$

$$\langle I_z \rangle = 2a^2 - 1 \quad \begin{cases} 1, & a=1, b=0 \\ 0, & a=b=1/\sqrt{2} \\ -1, & a=0, b=1 \end{cases}$$



I-13) Find the evolution operators, ^{UNITARY} OK 100 actually!

$$U_g(\phi_g) = e^{i\phi_g I_g} \quad (g = x, y, z)$$

use: 1) Pauli matrices

$$I_z = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \therefore S_z = \frac{2}{\hbar} I_z \Rightarrow \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$I_x = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \Rightarrow S_x = \frac{2}{\hbar} I_x \Rightarrow \sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$I_y = \frac{i}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \quad \Rightarrow S_y = \frac{2}{\hbar} I_y \Rightarrow \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

2) use Taylor expansion

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$$

$$\sigma_y = 2 I_y \quad \sigma_x = 2 I_x$$

$$\sigma_z = 2 I_z$$

3) use identity

$$e^{i u} = \left(1 - \frac{u^2}{2!} + \frac{u^4}{4!} - \dots \right) + i \left(\frac{u}{1!} - \frac{u^3}{3!} + \frac{u^5}{5!} - \dots \right)$$

$$= \cos(u) + i \sin(u)$$

4) use

$$\sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\sigma_z^2 = \mathbb{1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \sigma_x^2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1}$$

$$\sigma_z^3 = \mathbb{1} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \sigma_z \quad \sigma_x^3 = \sigma_x$$

$$\sigma_z^4 = \mathbb{1} \quad \sigma_x^4 = \mathbb{1}$$

$$\sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = i \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$\sigma_y^2 = i^2 \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = -1 \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} = \mathbb{1}$$

$$\sigma_y^3 = \sigma_y$$

$$\sigma_y^4 = \mathbb{1}$$

Find The matrix expressions FOR $e^{i\sigma_z \phi_z}$ { kind of combined

#B
 $e^{i\phi_z \sigma_z} = e^{i(\frac{\phi_z}{2}) 2I_z} = e^{i\alpha_z \sigma_z}$

I-13, 14 here
 $2I_z = \sigma_z$
 $\alpha_z = (\frac{\phi_z}{2})$
 Don't Forget

$$e^{i\alpha_z \sigma_z} = 1 + \frac{i\alpha_z \sigma_z}{1} + \frac{i^2 \alpha_z^2 \sigma_z^2}{2!} + \frac{i^3 \alpha_z^3 \sigma_z^3}{3!} + \frac{(i\alpha_z \sigma_z)^4}{4!} + \dots$$

$$= \left(1 - \frac{\alpha_z^2 \sigma_z^2}{2!} + \frac{\alpha_z^4 \sigma_z^4}{4!} + \dots \right) + i \left(\frac{\alpha_z \sigma_z}{1} - \frac{\alpha_z^3 \sigma_z^3}{3!} + \frac{\alpha_z^5 \sigma_z^5}{5!} - \dots \right)$$

$$\sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \sigma_z^2 = \mathbb{1} \quad \sigma_z^4 = \mathbb{1}$$

$$\sigma_z^3 = \sigma_z \quad \sigma_z^5 = \sigma_z$$

$$e^{i\alpha_z \sigma_z} = \cos(\alpha_z) + i \sigma_z \sin(\alpha_z)$$

$$e^{i\alpha_z \sigma_z} = \cos(\alpha_z) + i \sigma_z \sin(\alpha_z)$$

$$\alpha_z = \frac{\phi_z}{2}$$

$$\sigma_z = 2I_z$$

Summary

$$e^{i\phi_z I_z} = c(\alpha_z) + i \sigma_z s(\alpha_z)$$

$$e^{i\phi_x I_x} = c(\alpha_x) + i \sigma_x s(\alpha_x)$$

$$e^{i\phi_y I_y} = c(\alpha_y) + i \sigma_y s(\alpha_y)$$

$$\alpha = \frac{\phi}{2} \quad \begin{matrix} x, y, z \\ \end{matrix}$$

$$\sigma = 2I$$

$$e^{i\phi_x I_x} = e^{i\left(\frac{\phi_x}{\hbar}\right) 2I_x} = e^{i\alpha_x \sigma_x}$$

$$\alpha_x = \left(\frac{\phi_x}{\hbar}\right)$$

$$e^{i\alpha_x \sigma_x} = \cos(\alpha_x) + i\sigma_x \sin(\alpha_x)$$

$$\sigma_x = 2I_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$e^{i\phi_y I_y} = e^{i\left(\frac{\phi_y}{\hbar}\right) 2I_y} = e^{i\alpha_y \sigma_y}$$

$$\alpha_y = \frac{\phi_y}{\hbar}$$

$$\sigma_y = 2I_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$e^{i\alpha_y \sigma_y} = \cos(\alpha_y) \mathbb{1} + i\sin(\alpha_y) \sigma_y$$

$$e^{i\phi_y I_y} = \cos(\alpha_y) \mathbb{1} + i\sigma_y \sin(\alpha_y)$$

could expand these like:

$$e^{i\phi_x I_x} = c(\alpha_x) + i\sigma_x \sin(\alpha_x)$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} c(\alpha_x) + i \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \sin(\alpha_x)$$

$$= \begin{pmatrix} c(\alpha_x) & 0 \\ 0 & c(\alpha_x) \end{pmatrix} + \begin{pmatrix} 0 & i\sin(\alpha_x) \\ i\sin(\alpha_x) & 0 \end{pmatrix}$$

$$e^{i\phi_x I_x} = \begin{pmatrix} c(\alpha_x) & i\sin(\alpha_x) \\ i\sin(\alpha_x) & c(\alpha_x) \end{pmatrix}$$

$$= c(\alpha_x) + i\sigma_x \sin(\alpha_x)$$

$$I_z \xrightarrow{u_x} = e^{i\phi_x I_x} I_z e^{-i\phi_x I_x} = e^{i(\frac{\phi_x}{\hbar}) 2I_x} \left(\frac{\sigma_z}{2}\right) e^{-i(\frac{\phi_x}{\hbar}) 2I_x}$$

I-14

$$= e^{i\alpha_x \sigma_x} \left(\frac{\sigma_z}{2}\right) e^{-i\alpha_x \sigma_x}$$

$$\begin{aligned} \sigma_x &= 2I_x \\ \sigma_z &= 2I_z \\ \alpha_x &= \frac{\phi_x}{\hbar} \end{aligned}$$

$$= \frac{1}{2} [C(\alpha_x) + i\sigma_x S(\alpha_x)] \sigma_z [C(\alpha_x) - i\sigma_x S(\alpha_x)]$$

* TYPE ROTATIONS

see HWWK I-14

I_x

$$\begin{aligned} u_x &\rightarrow I_x \\ u_y &\rightarrow I_x \cos(\phi_y) + I_z \sin(\phi_y) \\ u_z &\rightarrow I_x \cos(\phi_z) - I_y \sin(\phi_z) \end{aligned}$$

I_y

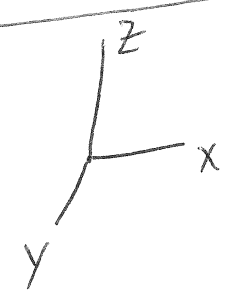
$$\begin{aligned} u_x &\rightarrow I_y \cos(\phi_x) - I_z \sin(\phi_x) \\ u_y &\rightarrow I_y \\ u_z &\rightarrow I_y \cos(\phi_z) + I_x \sin(\phi_z) \end{aligned}$$

I_z

$$\begin{aligned} u_x &\rightarrow I_z \cos(\phi_x) + I_y \sin(\phi_x) \\ u_y &\rightarrow I_z \cos(\phi_y) - I_x \sin(\phi_y) \\ u_z &\rightarrow I_z \end{aligned}$$

convention

$$\begin{aligned} \sigma_x \sigma_y &= i\sigma_z & \sigma_y \sigma_x &= -i\sigma_z \\ \sigma_y \sigma_z &= i\sigma_x & \sigma_z \sigma_y &= -i\sigma_x \\ \sigma_z \sigma_x &= i\sigma_y & \sigma_x \sigma_z &= -i\sigma_y \end{aligned}$$



$$I_y \xrightarrow{\psi_z} U_z I_z U_z^{-1} = [C(\alpha_z) + i\sigma_z S(\alpha_z)] \left(\frac{\sigma_y}{i} \right) [C(\alpha_z) - i\sigma_z S(\alpha_z)]$$

$$= \frac{1}{i} [C + i\sigma_z S] [\sigma_y C - i\sigma_z \sigma_y \sigma_z S]$$

$$= \frac{1}{i} [C^2 \sigma_y - i C \sigma_y \sigma_z S + (i\sigma_z S)(\sigma_y C) - (i\sigma_z S)(i\sigma_y \sigma_z S)]$$

$$= \frac{1}{i} [C^2 \sigma_y - i C S \sigma_y \sigma_z + i C S \sigma_z \sigma_y - i^2 S^2 \sigma_z \sigma_y \sigma_z]$$

$$\begin{aligned} xy z & \sigma_z \sigma_y \sigma_z \\ yz x & = \sigma_z \sigma_x i = (-i\sigma_y i) i = -\sigma_y \\ zx y & = i \sigma_y = -\sigma_y \end{aligned}$$

$$= \frac{1}{i} [C^2 \sigma_y - i C S (i \sigma_x) + i C S (-i \sigma_x) - i^2 S^2 (-\sigma_y)]$$

$$= \frac{1}{i} [C^2 \sigma_y - i^2 C S \sigma_x - i^2 C S \sigma_x - i^2 S^2 (-\sigma_y)]$$

$$= \frac{1}{i} [C^2 \sigma_y + C S \sigma_x + C S \sigma_x + S^2 \sigma_y]$$

$$= \frac{1}{i} [\sigma_y [C^2(\alpha_z) - S^2(\alpha_z)] + 2C(\alpha_z)S(\alpha_z) \sigma_x]$$

$$C(\alpha)S(\alpha) = \frac{S(2\alpha)}{2} \quad C^2(\alpha) - S^2(\alpha) = C(2\alpha)$$

$$= \frac{1}{i} \left[\sigma_y C(2\alpha_z) + \frac{2\sigma_x S(\alpha_z)}{i} \right] = \frac{1}{i} [\sigma_y C(2\alpha_z) + S(2\alpha_z) \sigma_x]$$

$$\begin{aligned} \sigma_y &= 2I_x \\ \sigma_x &= 2I_y \end{aligned}$$

$$\frac{1}{i} \left[2I_x C\left(\frac{2\phi_z}{2}\right) + 2I_y S\left(\frac{2\phi_z}{2}\right) \right]$$

$$I_y \xrightarrow{\psi_z} I_x \cos(\phi_z) + I_y \sin(\phi_z)$$



$$I_y \xrightarrow{\phi_x} e^{i\phi_x I_x} I_y e^{-i\phi_x I_x} = e^{i(\frac{\phi_x}{2}) 2I_x} \left(\frac{\sigma_y}{2}\right) e^{-i(\frac{\phi_x}{2}) 2I_x}$$

$$= \frac{1}{2} e^{i\phi_x \sigma_x} \sigma_y e^{-i\phi_x \sigma_x}$$

$$\boxed{\begin{aligned} \sigma_x &= 2I_x & \alpha_x &= \left(\frac{\phi_x}{2}\right) \\ \sigma_y &= 2I_y \end{aligned}}$$

$$= \frac{1}{2} [c + i\sigma_x s] \sigma_y [c - i\sigma_x s]$$

$$= \frac{1}{2} [c + i\sigma_x s] [\sigma_y c - \sigma_y i\sigma_x s]$$

$$= \frac{1}{2} [c + i\sigma_x s] [c\sigma_y - i s \sigma_y \sigma_x]$$

$$= \frac{1}{2} [cc\sigma_y - i c s \sigma_y \sigma_x + (i\sigma_x s)(c\sigma_y) - (i\sigma_x s)(i s \sigma_y \sigma_x)]$$

$$= \frac{1}{2} [c^2 \sigma_y - i c s \sigma_y \sigma_x + i c s \sigma_x \sigma_y - i^2 s^2 \sigma_x \sigma_y \sigma_x]$$

$$\begin{aligned} \sigma_x \sigma_y &= i\sigma_z \\ \sigma_y \sigma_x &= -i\sigma_z \end{aligned}$$

$$\begin{aligned} \sigma_x \sigma_y \sigma_x &= \sigma_x (-i\sigma_z) \\ &= -i(\sigma_x \sigma_z) \\ -\sigma_y &= -i(-i\sigma_y) \end{aligned}$$

$$= \frac{1}{2} [c^2 \sigma_y - i c s (-i\sigma_z) + i c s (i\sigma_z) - i^2 s^2 (-\sigma_y)]$$

$$= \frac{1}{2} [c^2 \sigma_y + i^2 c s \sigma_z + i^2 c s \sigma_z + i^2 s^2 \sigma_y]$$

$$= \frac{1}{2} [c^2 \sigma_y - c s \sigma_z - c s \sigma_z - s^2 \sigma_y]$$

$$c(2\alpha) s(\alpha) = \frac{s(2\alpha)}{2}$$

$$c^2(2\alpha) - s^2(2\alpha) = c(2\alpha)$$

$$= \frac{1}{2} \left[\sigma_y c(2\alpha_x) - 2 \left(\frac{s(2\alpha_x)}{2} \right) \sigma_z \right]$$

$$= \frac{1}{2} [\sigma_y \cos(2\alpha_x) - s(2\alpha_x) \sigma_z]$$

$$= \frac{1}{2} [2I_y \cos\left(\frac{2\phi_x}{2}\right) - 2I_z \sin\left(\frac{2\phi_x}{2}\right)]$$

$$\begin{aligned} \sigma_z &= 2I_z \\ \sigma_y &= 2I_y \\ \alpha_x &= \frac{\phi_x}{2} \end{aligned}$$

$$\Rightarrow I_y \xrightarrow{\phi_x} \boxed{I_y \cos(\phi_x) - I_z \sin(\phi_x)}$$

$$I_x \xrightarrow{u_y(\phi_y)} e^{2\phi_y I_y} I_x e^{-2\phi_y I_y} \quad \sigma_x = 2I_x \quad \therefore I_x = \frac{\sigma_x}{2}$$

$$= e^{2\phi_y I_y} \left(\frac{\sigma_x}{2} \right) e^{-2\phi_y I_y} \quad \sigma_y = 2I_y \quad \alpha_y = \frac{\phi_y}{2}$$

$$= e^{2\alpha_y \sigma_y} \left(\frac{\sigma_x}{2} \right) e^{-2\alpha_y \sigma_y} \quad e^{2\alpha_y \sigma_y} = U_y = C(\alpha_y) + i\sigma_y S(\alpha_y)$$

$$= (C + i\sigma_y S) \left(\frac{\sigma_x}{2} \right) (C - i\sigma_y S)$$

$$= \frac{1}{2} (C + i\sigma_y S) [C\sigma_x - i\sigma_x \sigma_y S]$$

$$= \frac{1}{2} \left[C \cdot C\sigma_x - i C\sigma_x \sigma_y S + (i\sigma_y S)(C\sigma_x) - i^2 \sigma_y^2 S\sigma_x \sigma_y S \right]$$

$$= \frac{1}{2} [C^2 \sigma_x - i C S \sigma_x \sigma_y + i C S \sigma_y \sigma_x - i^2 S^2 \sigma_y \sigma_x \sigma_y]$$

$\sigma_x \sigma_y = i\sigma_z$	$\sigma_y \sigma_x \sigma_y$	$x \quad y \quad z$
$y \sigma_y = -i\sigma_z$	$\sigma_y (i\sigma_z)$	$y \quad z \quad x$
	$i (i\sigma_x) = -\sigma_x$	$z \quad x \quad y$

$$= \frac{1}{2} [C^2 \sigma_x - i C S (i\sigma_z) + i C S (-i\sigma_z) - i^2 S^2 (-\sigma_x)]$$

$$= \frac{1}{2} [C^2 \sigma_x - i^2 C S \sigma_z + i^2 C S \sigma_z + i^2 S^2 \sigma_x]$$

$$= \frac{1}{2} [C^2 \sigma_x + C S \sigma_z + C S \sigma_z - S^2 \sigma_x]$$

$$= \frac{1}{2} [\sigma_x [C^2 - S^2] + 2 C S \sigma_z]$$

$$\boxed{C(2\alpha) S(2\alpha) - \frac{S(2\alpha)}{2}}$$

$$\boxed{C^2(2\alpha) - S^2(2\alpha) = C(2\alpha)}$$

$$= \frac{1}{2} \left[\sigma_x \cos(2\alpha_y) + 2 \left(\frac{\sin(2\alpha_y)}{2} \right) \sigma_z \right]$$

$$= \frac{1}{2} [\sigma_x \cos(2\alpha) + \sin(2\alpha) \sigma_z]$$

$$= \frac{1}{2} [2I_x \cos\left(\frac{2\phi_y}{2}\right) + 2I_z \sin\left(\frac{2\phi_y}{2}\right)]$$

$$\boxed{I_x \xrightarrow{u_y} = I_x \cos(\phi_y) + I_z \sin(\phi_y)}$$

$$\alpha_y = \frac{\phi_y}{2}$$

$$\sigma_x = 2I_x$$

$$\sigma_z = 2I_z$$

$$I_x \xrightarrow{u_z(\alpha)} e^{i\sigma_x I_z} I_x e^{-i\sigma_x I_z} = \sigma_x = \alpha I_x$$

$$= \left[c(\alpha z) + i\sigma_z s(\alpha z) \right] \left(\frac{\sigma_x}{\alpha} \right) \left[c(\alpha z) - i\sigma_z s(\alpha z) \right]$$

$$= (c + i\sigma_z s) \frac{1}{\alpha} [c\sigma_x - i\sigma_x\sigma_z s]$$

$$= \frac{1}{\alpha} [c(c\sigma_x) + c(-i\sigma_x\sigma_z s) + i\sigma_z s(c\sigma_x) + i\sigma_z s(-i\sigma_x\sigma_z s)]$$

$$= \frac{1}{\alpha} [c^2\sigma_x - i c s \sigma_x\sigma_z + i c s \sigma_z\sigma_x - i^2 s^2 \sigma_z\sigma_x\sigma_z]$$

$\sigma_x\sigma_y = i\sigma_z$ $\begin{matrix} xy & z \\ yz & x \\ zx & y \end{matrix}$ $\text{else } (-i\sigma_e)$

$$= \frac{1}{\alpha} [c^2\sigma_x - i c s (-i\sigma_y) + i c s (+i\sigma_y) - i^2 s^2 (-\sigma_x)]$$

$$= \frac{1}{\alpha} [c^2\sigma_x - c s \sigma_y + i^2 c s \sigma_y - s^2 \sigma_x]$$

$$= \frac{1}{\alpha} [c^2\sigma_x - s^2\sigma_x] - 2 c s \sigma_y$$

$$c(\alpha) s(\beta) = \frac{s(\alpha+\beta) + s(\alpha-\beta)}{2}$$

$$c(\alpha) c(\beta) - s(\alpha) s(\beta) = c(\alpha+\beta)$$

$$= \frac{1}{\alpha} [c(\alpha z) c(\alpha z)]$$

$$= \frac{1}{2} [c^2(\alpha z) \sigma_x - s^2(\alpha z) \sigma_x] - 2c(\alpha z) s(\alpha z) \sigma_y$$

$$= \frac{1}{2} [\sigma_x c(2\alpha z) - 2 \frac{s(2\alpha z) + s(\phi)}{2}] \sigma_y \quad s(0) = 0$$

$$= \frac{1}{2} [\sigma_x c(2\alpha z) - \sigma_y s(2\alpha z)] \quad \alpha z = \frac{\phi z}{2}$$

$$I_x \xrightarrow{u_x(t)} \frac{1}{2} [\sigma_x \cos(\phi z) - \sigma_y \sin(\phi z)]$$

$$= \frac{1}{2} [2I_x \cos(\phi z) - 2I_y \sin(\phi z)]$$

$$I_x(\frac{\phi z}{2}) = I_x \cos(\phi z) - I_y \sin(\phi z) \quad \checkmark$$

$$u_z \xrightarrow{I_z} u_z I_z u_z$$

$$= [c(\alpha z) + e \sigma_z s(\alpha z)] \left(\frac{\sigma_z}{2} \right) [c(\alpha z) - e s(\alpha z) \sigma_z]$$

$$= \frac{1}{2} [c + e \sigma_z s] [c \sigma_z - e s \sigma_z \sigma_z]$$

$$= \frac{1}{2} [c^2 \sigma_z - e c s \sigma_z^2 + e \sigma_z s c \sigma_z - e^2 \sigma_z s s \sigma_z^2]$$

$$= \frac{1}{2} [c^2 \sigma_z - e c s + e c s - e^2 \sigma_z s^2]$$

$$= \frac{1}{2} [c^2 \sigma_z + s^2 \sigma_z] = \frac{1}{2} \sigma_z [c^2 + s^2] = \frac{1}{2} \sigma_z$$

$$\sigma_z = 2I_z \quad \therefore \quad I_z \xrightarrow{u_z} I_z$$

$$I_z \xrightarrow{u_x} e^{i\phi_x I_x} I_z e^{-i\phi_x I_x} = e^{i(\frac{\phi_x}{2}) 2I_x} \left(\frac{\sigma_z}{2}\right) e^{-i(\frac{\phi_x}{2}) 2I_x}$$

$$\begin{aligned} \sigma_x &= 2I_x \\ \sigma_z &= 2I_z \\ \sigma_y &= \left(\frac{\phi_x}{2}\right) \end{aligned}$$

$$= \frac{1}{2} e^{i\alpha \times \sigma_x} \sigma_z e^{-i\alpha \times \sigma_x}$$

$$= \frac{1}{2} [c + i\sigma_x s] \sigma_z [c - i\sigma_x s]$$

$$= \frac{1}{2} [c + i\sigma_x s] [\sigma_z c - \sigma_z i\sigma_x s]$$

$$= \frac{1}{2} [c + i\sigma_x s] [c\sigma_z - i\sigma_z\sigma_x s]$$

$$= \frac{1}{2} [cc\sigma_z - ci\sigma_z\sigma_x s + (i\sigma_x s)(c\sigma_z) - (i\sigma_x s)(i\sigma_z\sigma_x s)]$$

$$= \frac{1}{2} [c^2\sigma_z - ci\sigma_z\sigma_x s + i c s \sigma_x \sigma_z - i^2 s^2 \sigma_x \sigma_z \sigma_x]$$

$\sigma_z \sigma_x = i\sigma_y$	$x \neq z$	$\sigma_x \sigma_z \sigma_x = \sigma_x (i\sigma_y) = i(\sigma_x \sigma_y) = i(-\sigma_z) = -i\sigma_z$
$\sigma_x \sigma_z = -i\sigma_y$	$z \neq x$	$\sigma_x (i\sigma_y) = i(\sigma_x \sigma_y) = i(-\sigma_z) = -i\sigma_z$

$$= \frac{1}{2} [c^2\sigma_z - ci\sigma_z\sigma_x s + i c s (-i\sigma_y) - i^2 s^2 (-\sigma_z)]$$

$$= \frac{1}{2} [c^2\sigma_z - c^2 c s \sigma_y - c^2 c s \sigma_y + c^2 s^2 \sigma_z]$$

$$= \frac{1}{2} [c^2\sigma_z + c s \sigma_y + c s \sigma_y - s^2 \sigma_z]$$

$$c^2(\alpha) - s^2(\alpha) = c(2\alpha) \quad c(\alpha)s(\alpha) = \frac{s(2\alpha)}{2}$$

$$= \frac{1}{2} [\sigma_z c(2\alpha_x) + 2 \left(\frac{s(2\alpha_x)}{2}\right) \sigma_y]$$

$$\begin{aligned} \sigma_z &= 2I_z \\ \sigma_x & \end{aligned}$$

$$= \frac{1}{2} [\sigma_z \cos(2\alpha_x) + \sin(2\alpha_x) \sigma_y]$$

$$= \frac{1}{2} [2I_z \cos\left(\frac{2\phi_x}{2}\right) + 2I_y \sin\left(\frac{2\phi_x}{2}\right)]$$

$$= I_z \cos(\phi_x) + I_y \sin(\phi_x) \Rightarrow I_z \xrightarrow{u_x}$$

$$I_z \xrightarrow{\psi_y} e^{i\phi_y I_y} I_z e^{-i\phi_y I_y} = e^{i(\frac{\phi_y}{2}) 2I_y} \left(\frac{\sigma_z}{2}\right) e^{-i(\frac{\phi_y}{2}) 2I_y}$$

$$= \frac{1}{2} e^{i\phi_y \sigma_y} \sigma_z e^{-i\phi_y \sigma_y}$$

$$\boxed{\begin{aligned} \sigma_y &= 2I_y & \sigma_z &= 2I_z \\ \alpha\psi &= \frac{\phi_y}{2} \end{aligned}}$$

$$= \frac{1}{2} [c + i s \sigma_y] \sigma_z [c - i s \sigma_y]$$

$$= \frac{1}{2} [c + i s \sigma_y] [\sigma_z c - \sigma_z i s \sigma_y]$$

$$= \frac{1}{2} [c + i s \sigma_y] [c \sigma_z - i s \sigma_z \sigma_y]$$

$$= \frac{1}{2} [c c \sigma_z - i c s \sigma_z \sigma_y + (i s \sigma_y)(c \sigma_z) - (i s \sigma_y)(i s \sigma_z \sigma_y)]$$

$$= \frac{1}{2} [c^2 \sigma_z - i c s \sigma_z \sigma_y + i c s \sigma_y \sigma_z - i^2 s^2 \sigma_y \sigma_z \sigma_y]$$

$$\begin{aligned} \sigma_z \sigma_y &= -i \sigma_x \\ \sigma_y \sigma_z &= i \sigma_x \end{aligned}$$

$$\begin{aligned} \sigma_x \sigma_y &= i \sigma_z \\ yz &= x \\ zx &= y \end{aligned}$$

$$\begin{aligned} \sigma_y \sigma_z \sigma_y &= \sigma_y (-i \sigma_x) \\ &= -i (\sigma_y \sigma_x) = -i (-i \sigma_z) \\ &= -\sigma_z \end{aligned}$$

$$= \frac{1}{2} [c^2 \sigma_z - i c s (-i \sigma_x) + i c s (i \sigma_x) - i^2 s^2 (-\sigma_z)]$$

$$= \frac{1}{2} [c^2 \sigma_z + i^2 c s \sigma_x + i^2 c s \sigma_x + c^2 s^2 \sigma_z]$$

$$= \frac{1}{2} [c^2 \sigma_z - 2 c s \sigma_x - s^2 \sigma_z]$$

$$c^2(\alpha) - s^2(\alpha) = c(2\alpha) \quad c(2/s(\alpha)) = \frac{s(2\alpha)}{2}$$

$$= \frac{1}{2} [\sigma_z c(2\alpha) - 2 \left(\frac{\sin(2\alpha)}{2} \right) \sigma_x]$$

$$\alpha\psi = \frac{\phi_y}{2}$$

$$\begin{aligned} \sigma_x &= 2I_x \\ \sigma_z &= 2I_z \end{aligned}$$

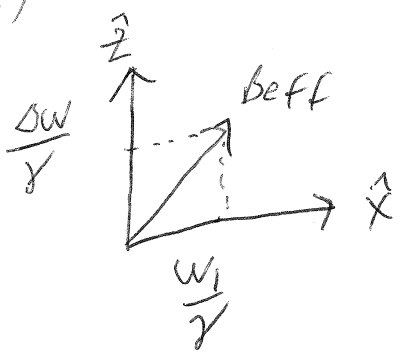
$$= \frac{1}{2} [2I_z \cos\left(\frac{2 \times \phi_y}{2}\right) - \sin\left(\frac{2 \times \phi_y}{2}\right) (2I_x)]$$

$$= I_z \cos(\phi_y) - \frac{I_x \sin(\phi_y)}{1} \Rightarrow I_z \xrightarrow{\psi_y}$$

I-15) IN THE PRESENCE OF b_1 FIELD OSCILLATING AT RATE ω_1

$$B_{eff} = \frac{1}{\gamma} (\Delta\omega \hat{z} + \omega_1 \hat{x}) = \frac{b_1}{\gamma} \hat{x} + (b_0 - \frac{\omega}{\gamma}) \hat{z}$$

e) calculate the precession rate of magnetization $\omega = \gamma b_0 = \gamma B_{eff}$



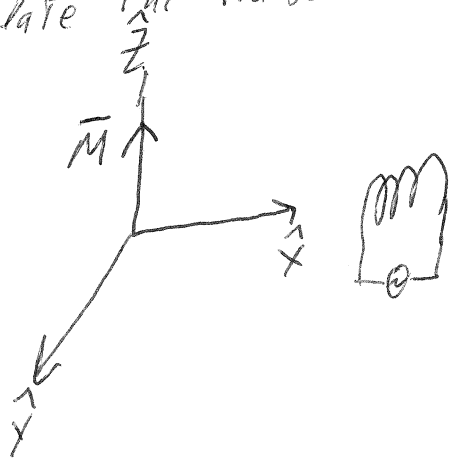
$$x^2 + y^2 = z^2$$

$$B_{eff} = \sqrt{\left(\frac{\Delta\omega}{\gamma}\right)^2 + \left(\frac{\omega_1}{\gamma}\right)^2}$$

$$\therefore \omega = \gamma B_{eff} = \gamma \sqrt{\left(\frac{\Delta\omega}{\gamma}\right)^2 + \left(\frac{\omega_1}{\gamma}\right)^2}$$

$$\tan\left(\frac{\Delta\omega}{\omega_1}\right) = \frac{B_{eff}}{1}$$

cc) calculate the trajectory of M if $M(t=0) = (0, 0, M_0)$



this is $U_x M_z U_x$ rotation

$$M(t) = M_z C(\omega t) + M_y S(\omega t)$$

* see I-14 unitary ops

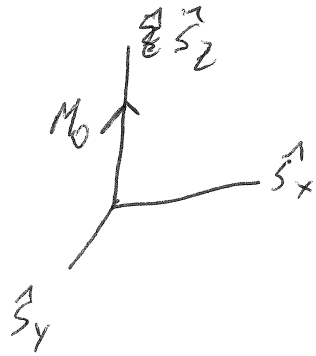
Lowes

$$H_z = -\hbar (\omega_0 - \omega) S_z - \hbar \omega_1 S_x$$

$$\omega_0 - \omega = 0$$

$$H_z = -\hbar \omega_1 S_x$$

15-20) Calculate The Trajectory of M if $M(t=0) = (0, 0, M_0)$



$$\rho(t=0) = M_0 s_z$$

ROTATION
ORDER MATTERS!
1ST - X
2ND - Z

Let $\omega_0 - \omega = \Delta = \text{offset}$

$$\hat{H}_r = -\hbar(\omega_0 - \omega) s_z - \hbar \omega_1 s_x$$

$$\rho(t) = e(-\frac{i\hat{H}t}{\hbar}) \rho(t=0) e(\frac{i\hat{H}t}{\hbar})$$

$$= e(i\Delta\omega t) M_0 s_z e(-i\omega t)$$

$$= e(i[\Delta\omega t s_z + \omega_1 t s_x]) M_0 s_z e(-i[\Delta\omega t s_z + \omega_1 t s_x])$$

$$= e(i\Delta\omega t s_z) e(i\omega_1 t s_x) M_0 s_z e(-i\Delta\omega t s_z) e(-i\omega_1 t s_x)$$

Let $\Delta\omega t = \phi_z$ $\omega_1 t = \theta$

$$e(i\phi_z s_z) e(i\theta s_x) M_0 s_z e(-i\theta s_x) e(-i\phi_z s_z)$$

$$M_0 [u_z(\phi) u_x(\theta) s_z u_x^{-1}(\theta) u_z^{-1}(\phi)]$$

See I-14 probs
unitary ops

$$\rho(t) = M_0 u_z(\phi) [s_z c(\theta) + s_y s(\theta)] u_z^{-1}(\phi)$$

$$P(t) = M_0 \left\{ U_{\underline{z}}(\phi) S_z C(\theta) U_{\underline{z}}^{-1}(\phi) + U_{\underline{z}}(\phi) S_y S(\theta) U_{\underline{z}}^{-1}(\phi) \right\}$$

$$= M_0 C(\theta) \left[U_{\underline{z}}(\phi) S_z U_{\underline{z}}^{-1}(\phi) \right] + M_0 S(\theta) \left[U_{\underline{z}}(\phi) S_y U_{\underline{z}}^{-1}(\phi) \right]$$

$$P(t) = M_0 C(\theta) S_z + M_0 S(\theta) \left[S_y C(\phi) + S_x S(\phi) \right]$$

$$\theta = \omega_1 t$$

$$\phi = \Delta \omega t$$

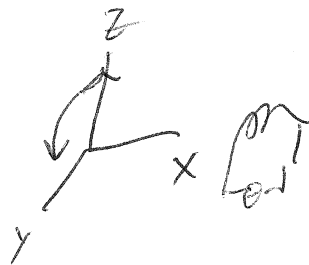
$$P(t) = M_0 \cos(\omega_1 t) S_z + M_0 \sin(\omega_1 t) \left[S_y \cos(\Delta \omega t) + S_x \sin(\Delta \omega t) \right]$$

rotating frame RF pulse w/offset

if $\Delta \omega = 0$

$$P(t) = M_0 C(\omega_1 t) S_z + M_0 S(\omega_1 t) S_y$$

$$= M_0 \left[C(\omega_1 t) S_z + S(\omega_1 t) S_y \right]$$



$$P(t) = M_0 \left\{ C(\omega_1 t) S_z + S(\omega_1 t) \left[S_y C(\Delta \omega t) + S_x S(\Delta \omega t) \right] \right\}$$

I-15) $\text{e}^{\text{e}^{\text{e}^{\text{e}}}}$) What range of ω_1 (as a function of $\Delta\omega$) are required to bring magnetization from Z into $X-Y$ plane?

$$\rho(t) = M_0 \gamma \left[C(\omega_1 t) S_z + S(\omega_1 t) [S_y C(\Delta\omega t) + S_x S(\Delta\omega t)] \right] \quad \text{Rot about } X$$

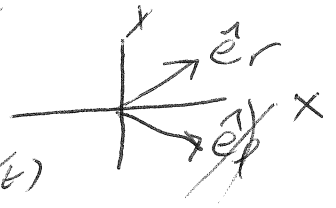
$$\omega_1 t \gg \Delta\omega t$$

$\text{e}^{\text{e}^{\text{e}^{\text{e}}}}$) Describe the phase that M_0 originally \parallel to Z - makes with ~~the~~ Y -axis as a f(ω) @ const = ω ,

Phase along Y -axis modulates @ $C(\Delta\omega t) \neq S(\omega_1 t)$

I-15) continued, have classical description of b_{eff} in rotating frame too.

$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \times \left[B_0 \hat{z} + \frac{B_1}{2} \hat{e}_r \right]$$

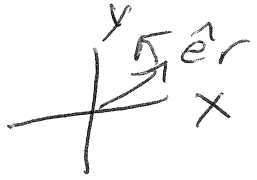


keeping just \hat{e}_r component $c(\omega t) + c(-\omega t)$

$$\begin{aligned} \vec{I} &= i_0 c(\omega t) \\ b &= b_0 c(\omega t) \end{aligned}$$

Lab
Frame
classic

$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \left[B_0 \hat{z} + \frac{b_1}{2} \left[c(\omega t) \hat{x} + s(\omega t) \hat{y} \right] \right]$$



$\omega = \gamma B$

Rotating
frame
classic

$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \left[\left(b_0 - \frac{\omega}{\gamma} \right) \hat{z} + \frac{b_1}{2} \hat{x} \right]$$

$$\begin{aligned} c(\omega t) \hat{x} + s(\omega t) \hat{y} \\ e^{i(\omega - \omega)t} = c(0) \end{aligned}$$

$$b_{eff} = \left(b_0 - \frac{\omega}{\gamma} \right) \hat{z} + \frac{b_1}{2} \hat{x}$$

To QM: irradiating a spin ensemble in Lab Frame

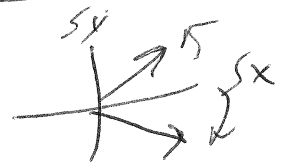
$$\partial_t \langle \hat{H}, \rho \rangle \quad \partial_t \hat{P} = [\hat{H}, \rho]$$

$$\hat{H} = -\vec{M} \cdot \vec{B} = -\gamma \hbar \left[B_0 \hat{S}_z + \frac{B_1}{2} c(\omega t) \hat{S}_x \right]$$

$$B_1 c(\omega t) \hat{S}_x \quad \frac{b_1}{2} \left[S_x c(\omega t) + S_y s(\omega t) \right]$$

has two components

$$+ \frac{b_1}{2} \left[S_x c(-\omega t) + S_y s(-\omega t) \right]$$



$$\therefore H = -\gamma \hbar \left[b_0 S_z + \frac{b_1}{2} \left[S_x c(\omega t) + S_y s(\omega t) \right] \right]$$

$$\omega_1 = \frac{\gamma b_1}{2}$$

$$H = -\hbar \omega_0 S_z - \hbar \omega_1 \left[S_x c(\omega t) + S_y s(\omega t) \right]$$

$$H = -\hbar\omega_0 S_z - \hbar\omega_1 [S_x \cos(\omega t) + S_y \sin(\omega t)] \quad \omega t = \phi$$

$$\dot{\psi} = \hat{H} \psi$$

$$\dot{\psi} = [H - eH] \psi =$$

$$\dot{\psi} = e^{-i\omega t S_z} [-\hbar\omega_0 S_z - \hbar\omega_1 S_x] e^{i\omega t S_z} \psi$$

LHP

$$\dot{\psi} = e^{-i\omega t S_z} [-\hbar\omega_0 S_z - \hbar\omega_1 S_x] e^{i\omega t S_z} \psi$$

LPH

* $e^{i\omega t S_z}$
 rotation about z for S_z flipping

$$\text{let } P = e^{i\omega t S_z} \quad e^{-i\omega t S_z}$$

rotation about \hat{z} @ ωt (wt)
 & now in rotating frame = ϕ

$$\dot{\psi} = \hat{H}_r \psi_r$$

$$\dot{\psi}_r = [H_r, P_r] \psi_r$$

$$H_r = -\hbar(\omega_0 - \omega) S_z - \hbar\omega_1 S_x$$

L & The field b_0 was reduced by $\frac{\omega}{\gamma}$, & b_1 looks static

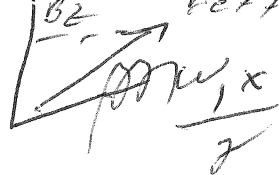
with Pauli matrices behave as:

$$\begin{aligned} \dot{a}_x(t) &= -\Delta\omega a_y \\ \dot{a}_y(t) &= \Delta\omega a_x + \omega_1 a_z \\ \dot{a}_z(t) &= -\omega_1 a_y \end{aligned}$$

$$\Delta\omega = \omega_1 - \omega = \text{offset}$$

$$\omega_1 = \frac{\gamma b_1}{2}$$

I-15) $\vec{B}_{eff} = \frac{1}{\gamma} (\Delta\omega, \vec{z} + \omega, \vec{x})$

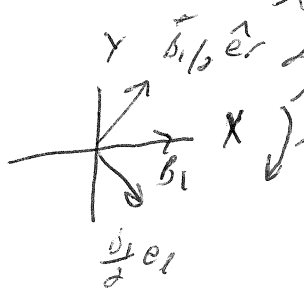


$\rho(t) = [H, \rho] \Rightarrow \rho(t) = e^{-\frac{iHt}{\hbar}} \rho(0) e^{\frac{iHt}{\hbar}}$
 Unitary ops again

$\rho(0)$ = time indep dens matr
 = state at time = 0

$\vec{H} = -\vec{\mu} \cdot \vec{B} = -\gamma \hbar B_0 S_z - \gamma \hbar B_1 C(\omega t) S_x$
 (new time dep term)

Review I.5 $I = I_0 C(\omega t)$
 = oscillating current



rotating components opposite direction
 drop \rightarrow drop $-\omega$

$\vec{B} = B_1 C(\omega t) \hat{x}$

The behavior of \vec{M} :

$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \times \vec{B}$$

$$= \gamma \vec{M} \times (B_0 \hat{z} + \frac{B_1}{\gamma} \hat{x})$$

$$= \gamma \vec{M} \times (B_0 \hat{z} + \frac{B_1}{2} [C(\omega t) \hat{x} + S(\omega t) \hat{y}])$$

$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \times (b_0 \hat{z} + \frac{b_1}{2} [c(\omega t) \hat{x} + s(\omega t) \hat{y}])$$

GO INTO ROTATING FRAME or here $b_1(\omega) \Rightarrow \therefore b_1$ looks static

$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \times \left[(b_0 - \frac{\omega}{\gamma}) \hat{z} + \frac{b_1}{2} \hat{x} \right]$$

$\omega = \gamma B_1$

Note in Rot Frame

$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \times \left[(b_0 - \frac{\omega}{\gamma}) \hat{z} + \frac{b_1}{2} [c(\omega - \omega)t \hat{x} + s(\omega - \omega)t \hat{y}] \right]$$

$$= \gamma \vec{M} \times \left[(b_0 - \frac{\omega}{\gamma}) \hat{z} + \frac{b_1}{2} [c(0) \hat{x} + s(0) \hat{y}] \right]$$

B_0 *

$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \times \left[(b_0 - \frac{\omega}{\gamma}) \hat{z} + \frac{b_1}{2} \hat{x} \right]$$

$$\frac{d\vec{M}}{dt} = \vec{M} \times \left[(\gamma b_0 - \omega) \hat{z} + \frac{\gamma b_1}{2} \hat{x} \right]$$

$$\omega_1 = \frac{\gamma b_1}{2}$$

$\omega_0 - \omega = \text{offset}$

* $\frac{d\vec{M}}{dt} = \vec{M} \times \left[(\omega_0 - \omega) \hat{z} + \frac{\omega_1}{2} \hat{x} \right]$

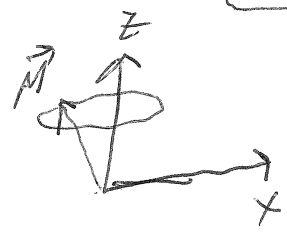
IN THE ROTATING FRAME there is Precession of \vec{M} about;

$$\vec{B}_{\text{eff}} = \frac{b_1}{2} \hat{x} + (b_0 - \frac{\omega}{\gamma}) \hat{z}$$

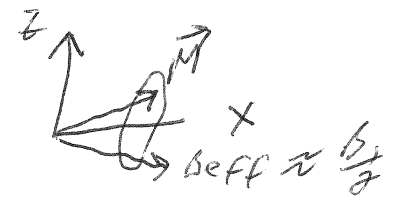
$$\omega = \gamma B$$

when $B = b_0$

$$B_{\text{eff}} = B_1/2$$



$$B_{\text{eff}} \approx b_0 - \frac{\omega}{\gamma}$$



J-16) Calculate the EV's & ES's for:

$$Hr = -\Delta W I_z - I_x W_1$$

$$\Delta W = W_0 - W$$

$$W_1 = \frac{\gamma \delta_1}{2}$$

offset in rotating frame

$$I_z = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad I_x = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

~~$$Hr = -\Delta W$$~~

$$Hr = -\frac{\Delta W}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} - \frac{1}{2} W_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$Hr = \frac{1}{2} \begin{pmatrix} \Delta W & W_1 \\ W_1 & -\Delta W \end{pmatrix}$$

assume $EV = K$ $H\Psi = K\Psi$

Then $(H\Psi - K\Psi) = 0$

~~$$\det \begin{vmatrix} -\frac{1}{2}\Delta W - K & \frac{W_1}{2} \\ \frac{W_1}{2} & \frac{1}{2}\Delta W - K \end{vmatrix} = 0$$~~

~~$$(-\frac{\Delta W}{2} - K)(\frac{\Delta W}{2} - K) - \frac{W_1^2}{4} = 0$$~~

~~$$= (-\frac{\Delta W}{2})(\frac{\Delta W}{2}) - (\frac{K\Delta W}{2}) + \frac{K\Delta W}{2} + K^2 - \frac{W_1^2}{4} = 0$$~~

~~$$= K^2 - \frac{\Delta W^2}{4} - \frac{W_1^2}{4} = 0 \Rightarrow K^2 = \frac{\Delta W^2}{4} + \frac{W_1^2}{4}$$~~

~~$$K = \pm \frac{1}{2} \sqrt{\Delta W^2 + W_1^2} \quad \left. \begin{array}{l} \text{The} \\ \text{EV's} \end{array} \right\}$$~~

$$k = \frac{1}{2} \sqrt{\Delta\omega^2 + \omega_1^2} \quad L.$$

$$\begin{aligned} \langle X | & \begin{pmatrix} -\frac{1}{2}\Delta\omega - (k) & +\frac{\omega_1}{2} \\ \frac{\omega_1}{2} & \Delta\omega + k \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = 0 \\ \langle B | & \end{aligned} \quad \left\{ \begin{aligned} (-\frac{\Delta\omega}{2} - k)C_1 + \frac{\omega_1}{2}C_2 &= 0 \\ \frac{\omega_1}{2}C_1 + (\frac{\Delta\omega}{2} + k)C_2 &= 0 \end{aligned} \right.$$

$$C_1 \frac{\omega_1}{2} = \left(-\frac{\Delta\omega}{2} - \frac{1}{2} \sqrt{\Delta\omega^2 + \omega_1^2} \right) C_2$$

$$\begin{aligned} \text{Let } A &= -\frac{\Delta\omega}{2} - k \\ B &= \frac{\omega_1}{2} \end{aligned}$$

$$C_1 = \left(\frac{-\Delta\omega}{\omega_1} - \frac{\sqrt{\Delta\omega^2 + \omega_1^2}}{\omega_1} \right) C_2$$

$$C_1^2 + C_2^2 = 1$$

$$\left(\frac{-\Delta\omega}{\omega_1} - \frac{\sqrt{\Delta\omega^2 + \omega_1^2}}{\omega_1} \right) \left(\frac{-\Delta\omega}{\omega_1} - \frac{\sqrt{\Delta\omega^2 + \omega_1^2}}{\omega_1} \right) C_2^2 + C_2^2 = 1$$

$$C_1 A = \begin{pmatrix} A & B \\ D & -A \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = 0 \quad \begin{cases} AC_1 + BC_2 = 0 \\ BC_1 - AC_2 = 0 \end{cases}$$

$$BC_1 = AC_2$$

$$C_1 = \frac{AC_2}{B}$$

$$C_1^2 + C_2^2 = 1$$

$$\left(\frac{A^2}{B^2} \right) C_2^2 + C_2^2 = 1$$

$$C_2^2 \left(1 + \frac{A^2}{B^2} \right) = 1$$

$$\therefore C_2^2 = \frac{1}{1 + \frac{A^2}{B^2}} = 1 + \frac{B^2}{A^2}$$

$$C_2 = \sqrt{1 + \frac{B^2}{A^2}}$$

$$\therefore C_1 =$$

$$\begin{pmatrix} -\frac{i}{2}\Delta W - K & \frac{w_1}{2} \\ \frac{w_1}{2} & \frac{\Delta W}{2} + K \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$K = \frac{1}{2} \sqrt{\Delta W^2 + w_1^2} = \frac{1}{2} w_{\text{eff}}^2$$

$$A = -\frac{1}{2} \Delta W - K$$

$$\begin{pmatrix} A & B \\ B & -A \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{cases} Ac_1 + Bc_2 = 0 \\ Bc_1 - Ac_2 = 0 \end{cases}$$

$$Ac_1 = -Bc_2 \quad c_1 = \frac{-Bc_2}{A}$$

$$Bc_1 = Ac_2 \quad c_1 = \frac{A}{B} c_2$$

$$c_1^2 + c_2^2 = 1$$

$$\frac{A^2}{B^2} c_2^2 + c_2^2 = 1$$

$$c_2^2 \left(1 + \frac{A^2}{B^2} \right) = 1$$

$$\therefore c_2^2 = \frac{1}{1 + \frac{A^2}{B^2}} = \frac{\frac{B^2}{A^2}}{\frac{B^2}{A^2} + 1}$$

$$c_2 = \sqrt{\frac{1}{1 + \frac{A^2}{B^2}}}$$

$$\therefore c_1 = \frac{A}{B} \sqrt{\frac{1}{1 + \frac{A^2}{B^2}}}$$

$$\therefore K = \frac{1}{2} \sqrt{\Delta W^2 + w_1^2}$$

$$\Psi = c_1 |A\rangle + c_2 |B\rangle$$

$$\Psi = \frac{A}{B} \sqrt{\frac{1}{1 + \frac{A^2}{B^2}}} |A\rangle + \sqrt{\frac{1}{1 + \frac{A^2}{B^2}}} |B\rangle$$

$$A = -\frac{1}{2} \Delta W - \frac{1}{2} \sqrt{\Delta W^2 + w_1^2}$$

$$B = \frac{w_1}{2}$$

$$K = -\frac{1}{2} \sqrt{\Delta \omega_1^2 + \omega_1^2}$$

$$\begin{pmatrix} \frac{-\Delta \omega_1}{2} - K & \frac{\omega_1}{2} \\ \frac{\omega_1}{2} & \frac{\Delta \omega_1}{2} + K \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} A & B \\ B & -A \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$A = \frac{-\Delta \omega_1}{2} - K$$

$$A c_1 + B c_2 = 0$$

$$B c_1 = A c_2$$

$$B c_1 - A c_2 = 0$$

$$c_1 = \frac{A}{B} c_2$$

$$B = \frac{\omega_1}{2}$$

X same as before but K is DIFF SIGN

$$\Psi = c_1 | \alpha \beta \rangle + c_2 | \beta \alpha \rangle$$

$$c_1 = \frac{A}{B} \sqrt{\frac{1}{1 + \frac{A^2}{B^2}}}$$

$$c_2 = \sqrt{\frac{1}{1 + \frac{A^2}{B^2}}}$$

$$A = -\frac{\Delta \omega_1}{2} + \frac{1}{2} \sqrt{\Delta \omega_1^2 + \omega_1^2}$$

$$B = \frac{\omega_1}{2}$$

$$K = +\frac{K}{2} \sqrt{\Delta \omega_1^2 + \omega_1^2}$$

$$c_1 | \alpha \beta \rangle + c_2 | \beta \alpha \rangle$$

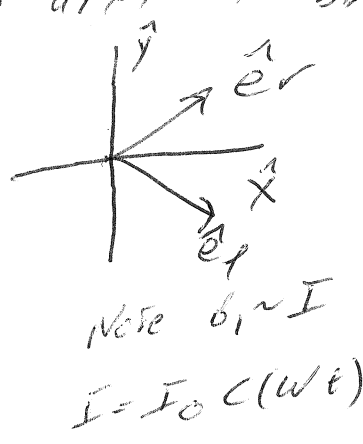
$$K = -\frac{1}{2} \sqrt{\Delta \omega_1^2 + \omega_1^2}$$

$$c_1 | \alpha \beta \rangle + c_2 | \beta \alpha \rangle$$

$$\Delta E = \sqrt{\Delta \omega_1^2 + \omega_1^2} = \text{Precession rate about Z}$$

From (c)

F-17) Show the equation for...
 aw NOT sure about this...



$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \times \left[B_0 \hat{z} + \frac{b_1}{\omega} \hat{e}_r + \frac{b_1}{\omega} \hat{e}_\theta \right]$$

$$= \gamma \vec{M} \times \left[B_0 \hat{z} + \frac{b_1}{\omega} \left[C(\omega t) + S(\omega t) \right] \right]$$

$$+ \frac{b_1}{\omega} \left[C(-\omega t) + S(-\omega t) \right]$$

Going to rotating frame subtract ω $\omega = \gamma B$

$$\frac{d\vec{M}}{dt} = \gamma \vec{M} \times \left[\left(B_0 - \frac{\omega}{\gamma} \right) \hat{z} + \frac{b_1}{\omega} \left[C((\omega - \omega)t) \hat{x} + S((\omega - \omega)t) \hat{y} \right] \right]$$

$$+ \frac{b_1}{\omega} \left[C((- \omega - \omega)t) \hat{x} + S((- \omega - \omega)t) \hat{y} \right]$$

A

$$\frac{d\vec{M}}{dt} = A + \frac{b_1}{\omega} \left[C(0) \hat{x} + S(0) \hat{y} \right] + \frac{b_1}{\omega} \left[C(-2\omega t) \hat{x} - S(-2\omega t) \hat{y} \right]$$

$$\frac{d\vec{M}}{dt} = A + \frac{b_1}{\omega} \hat{x} + \frac{b_1}{\omega} \left[C(-2\omega t) \hat{x} - S(-2\omega t) \hat{y} \right]$$

$$= c(\theta) e^{i\phi} I_x e^{-i\phi} + s(\theta) e^{-i\phi} I_y e^{i\phi} \quad \boxed{P(0) = I_x}$$

$$= c\theta [I_x c\phi - I_y s\phi] + s\theta [I_y c\phi + I_x s\phi]$$

$$= I_x c\theta c\phi - I_y c\theta s\phi + I_y s\theta c\phi + I_x s\theta s\phi$$

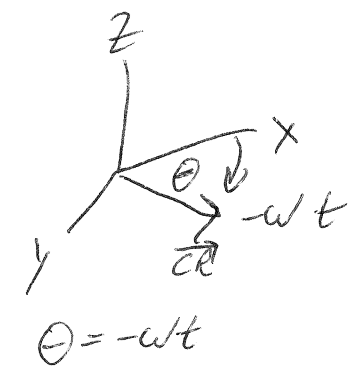
$$= I_x (c\theta c\phi + s\theta s\phi) + I_y [s\theta c\phi - c\theta s\phi]$$

$$= I_x c(\theta - \phi) + I_y [s\theta c\phi - c\theta s\phi]$$

$$= I_x c(\theta - \phi) + I_y s(\theta - \phi) = \boxed{\text{counter for component}}$$

note:

$$\vec{CR} = I_x c(\theta) + I_y s(\theta)$$



$\theta = \phi = -\omega t \Rightarrow I_x c(0) + I_y s(0) = I_x$ looks stationary

but in our rotating frame $\omega \phi = +\omega t, \theta = -\omega t$

$$= I_x c(\omega t - -\omega t) + I_y s(\omega t - -\omega t)$$

$$= I_x \cos(2\omega t) + I_y \sin(2\omega t)$$

Look up TRIG IDENTITIES:

- $\sin(\alpha + \beta) = s\alpha c\beta + c\alpha s\beta$
- $\cos(\alpha + \beta) = c\alpha c\beta - s\alpha s\beta$
- $\sin(\alpha - \beta) = s\alpha c\beta - c\alpha s\beta$
- $\cos(\alpha - \beta) = c\alpha c\beta + s\alpha s\beta$

$$s(2\theta) = 2 s\theta c\theta$$

$$c(2\theta) = c^2\theta - s^2\theta$$

$$s\alpha c\beta = \frac{s(\alpha + \beta) + s(\alpha - \beta)}{2}$$

$$\langle M, t \rangle = \gamma h \langle S_y \rangle \quad \text{for } s = \frac{\alpha}{2}, \frac{\beta}{2}$$

$$S_y = \frac{\hbar}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$\psi(t) = a e^{\frac{i(\omega_0 t + \alpha)}{2}} |a\rangle + b e^{\frac{i(-\omega_0 t + \beta)}{2}} |b\rangle$$

$$= a e^{iA} + b e^{iB}$$

$$\text{Let } A = \frac{\omega_0 t + \alpha}{2}$$

$$B = \frac{-\omega_0 t + \beta}{2}$$

$$\langle \psi(t) | \gamma h S_y | \psi(t) \rangle = \langle a e^{-iA} + b e^{-iB} | \gamma h S_y | a e^{iA} + b e^{iB} \rangle$$

$$\frac{\gamma h \hbar}{2} (a e^{-iA} + b e^{-iB}) \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a e^{iA} \\ b e^{iB} \end{pmatrix} = \begin{pmatrix} -b e^{iB} \\ a e^{iA} \end{pmatrix}$$

$$\phi = \alpha - \beta$$

$$= (-a b e^{-iA + iB} + a b e^{iA - iB}) \frac{\gamma h \hbar}{2}$$

$$A - B = \frac{\omega_0 t + \alpha}{2} - \left(\frac{-\omega_0 t + \beta}{2} \right) - B$$

$$= \omega_0 t + \phi$$

$$= \left(\frac{\gamma h \hbar}{2} \right) a b \left[-e^{i(\beta - \alpha)} + e^{i(\alpha - \beta)} \right]$$

$$B - A = \frac{-\omega_0 t + \beta}{2} - \frac{\omega_0 t + \alpha}{2} - \alpha$$

$$= -\omega_0 t - \phi$$

$$= c \left[-e^{i(-\omega_0 t + \phi)} + e^{i(\omega_0 t + \phi)} \right]$$

$$u = \omega_0 t + \phi$$

$$= c \left[-e^{i(u)} + e^{i(u)} \right]$$

$$= c \left[-[c(u) + e^{iS(u)}] + c(u) + e^{iS(u)} \right]$$

$$= c \left[-c(u) + e^{iS(u)} + c(u) + e^{iS(u)} \right]$$

$$= c \left[2 e^{iS(u)} \right]$$

$$= c [2 \cos(u)]$$

$$c = \frac{\Delta x c}{2} ab$$

$$= \frac{\gamma h c}{2} \cos(u) \cdot ab$$

$$u = \omega t + \phi$$

$$= -\gamma h c \sin(u) \cdot ab$$

$$= -\gamma h c \sin(\omega t + \phi) \cdot ab$$

$$c_{(t)} = (-ab \gamma h c) \sin(\omega t + \phi)$$