

Bruker BioSpin

AVANCE III

IPSO 19" & IPSO AQS

User Manual

Version 002

NMR Spectroscopy

think forward

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IPSO 19"

IPSO Manual IPSO AQS

Intelligent Pulse Sequenz Organizer (IPSO)

This Manual covers the spectrometer control unit called IPSO in versions:

- IPSO 19-inch
- IPSO AQS

which are used in the AVANCE III spectrometers

Chapter "1." summarizes the most essential informations for users to get started quickly and to avoid beginner's mistakes without reading plenty of pages.

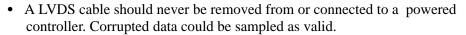
Chapter "2." lists the part/order numbers of the main assemblies, subassemblies and devices.

Chapter "3." et seq. provide the more detailed descriptions of assemblies and devices.

1. Condensed Introduction to the Essentials

Do's and Don'ts

• Do not connect a receiver to the LVDS connector of the controller in Slot2 of the IPSO 19" Unit. There will never be valid data.



• Do not connect more than one Gradient Amplifiers to the same system.

1. 1. Structure and Features

Features

- IPSO is a digital spectrometer control unit with a variable number of output channels (Tx-Controllers)
- Each Tx-Controller outputs a stream of 48-bit words at a clock rate of 80 MHz per word
- Transferral of a complete set of frequency parameters requires two words.
- The time resolution of parameter switching in any combination of Frequency, Phase, Amplitude is 12.5 nsec.
- The minimal duration of any combination of parameters is 25 nsec.
- Gradient channels require one word per gradient.
- The maximal number of addresses for different gradients (the max. number of gradient channels) is 1k.
- A constant time delay between the outputs of the different Tx-Controllers may be adjusted to any number of 80MHz clock cycles up to 2²⁹x12.5nsec

Structure

The distinctive Parts of the system are the Host Controller charged with administrative tasks, the number of Tx-Controllers generating and transferring the parameter sequences and the Sequencer providing for a means of communication between the Tx-Controllers.



The Controllers

The system contains the 3 types of controllers, Host Controller, Rx-Controller and the Tx-Controller.

Host Controller:

There is only one Host Controller in the system. The Host Controller is an IBM compatible PC with all standard interfaces thus making access possible to the whole pool of standard hardware and software.

The Host Controller boots its operating system software (diskless LI-NUX) from and communicates with the TOPSPIN-PC over Ethernet. It also communicates over its standard interfaces with the Rx– and the

Tx-Controllers and with peripheral devices.

RxController:

The Rx-Controller is able to receive 48-bit words at its LVDS interface at a rate of up to 100-Mega words. Therefore it can be used as a fast data link from the receiver channel to the transmit channel, bypassing the ethernet and the TOPSPIN-PC. Furthermore all Tx Controllers and their LVDS interfaces can be tested with the IPSOTEST if their interfaces are connected to a Rx-Controller.

Realtime processing of that data can be done by an onboard DSP. The processed data can be transferred by the DMA channels of the DSP

other controller.

Usually there is one Rx-Controller in the system. Without additional software (that means transparent to the software) it is possible to include additional Rx-Controllers using extension boxes.

over the system bus to any other controller or may be fetched by any

The Rx-Controller has no connections to the Sequencer and communicates and exchanges data with other controllers via the system bus. It will function in any slot of the IPSO but should be inserted in slot 1.

TxController:

Depending on its configuration, the Tx-Controller can be used for any of the 3 output functions in the system. These functions are the T-Controller servicing the RCP outputs at T0 with timing signals, the F-Controller generating the frequency parameters for the SGUs and the G-Controller generating the gradient packets for the amplifiers.

The Tx-Controllers and their common Sequencer are the most decisive parts of the IPSO system. The Sequencer is a single device, just one piece of silicon. It contains the communication and decision making logic of all Tx-Controllers and the communication bus between them known from former systems as the AQ-Bus. The AQ-Bus allows for real time communication on a 1-clock base of 12.5 nsec.

The controller itself consists of a DSP with memory, FIFO, output logic and interfaces to the system bus and the Sequencer. The DSP gets its code from the Host Controller, generates the parameter sequences and writes them into the FIFO. Its most important task is to keep the FIFO full. The Sequencer (once started) reads the words out of the FIFOs of all controllers, realizes the defined timing in each channel and controls the outputs.

The global functions of the Sequencer (e.g. START, STOP, SUS-PEND, RESUME and so on) are part of the Sequencer logic of the T-Controller. Therefore a T-Controller has to be in the system to carry out any type of acquisition.

LVDS

The LVDS cable is the transport media for digital data words between the Tx- and the Rx-Controllers respectively and the peripheral devices like SGU, Gradient Amplifier, DRU and DPP (Digital Preemphasis Processor). The abbreviation LVDS means "low voltage digital signal". The voltage switching range of the data lines is between 1.0V and 1.4V.

The used devices take 48-bit data words at a clock rate of 80MHz (and 100MHz between DRU and Rx-Controller respectively) and serialize and transport them over 8 balanced data line pairs accompanied by one clock pair. At the receiver side the data stream is deserialized and the 48-bit data word and its 80MHz clock are reconstructed.

Because there are 8 data lines, the cable has to transport 6 data bit plus one balance bit per 12,5nsec. That means a bit frequency of 560MHz on each data line. Since a good signal quality needs a good transmission behavior up to the fifth harmonic wave this cable has to transport the signals up to about 3–GHz without frequency dependent distortions.

The LVDS cable driver is always active even if the Tx-Controller is transmitting no valid data.

There are 2 options called "Deskew" and "Preemphasis" which are intended to compensate the negative influence of cables longer than about 3 meters to the signal quality. The usual cable length below 2 meters requires neither Deskew nor Preemphasis.

Deskew:

This feature minimizes the effective skew of the different data line pairs in the cable. To be effective it has to be enabled at the receiver and carried out at the transmitter. The default state at introduction is "NOT ENABLED" at the receiver and is activated at the transmitter by a software command only.

If enabled at the receiver Deskew has to be carried out after power—up and again each time after the cable has been plugged out and in under power. This can be done by software using the command "Deskew" of the "ipsotest" program.

Software activated Deskew needs TOPSPIN 2.0b6 and a Tx-Controller with Part# "H12538F2". Otherwise with "Deskew enabled at the receiver" the system has to be powered up again after reconnecting.

Preemphasis:

This feature compensates for the greater need of charge on cables longer than 2 meters. To be effective it needs one cable—length—dependent resistor at the transmitter. If ever necessary such Tx-Controllers will be given a special part number.

The state of the Tx-Controllers with part number "H15538" and "H15538F1" and H12538F2 is "NO PREEMPHASIS"

Besides the data and clock lines the LVDS cable includes 4 lines of an USB channel (unused so far) and 2 state lines. The state lines tell the Tx-Controller the kind of the connected device like "unconnected, SGU connected, Gradient Amplifier connected, DPP connected".





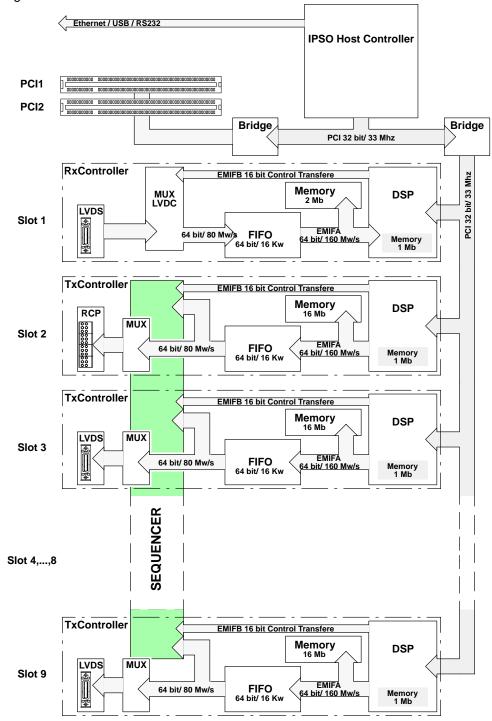
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IPSO 19"

IPSO Manual IPSO AQS

Figure 1: Block diagram of the IPSO 19" Unit



1. 2. Handling

ESD

Handling under ESD safety conditions is necessary.

Don't touch uncovered metal of PCB and connectors before discharging yourself!



Boot procedure

The IPSO needs to boot its diskless LINUX from the TOPSPIN–PC via the Ethernet. This connection with or without an hub included requires the following cable:

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Connection	Туре	Color	Part#	Length
	LITD/OATS		84338	5m
point-to-point	UTP/CAT5, crossed	red	83980	10m
	1170/0475		83025	5m
point-to-hub	UTP/CAT5, straight	white	83026	10m

If connected, the IPSO needs only to be switched on or to be resetted to begin booting.

Power ON/OFF Button

To be effective this button needs to be pressed for about 2 seconds to switch the system on and 6 seconds to switch it off.

Reset Button

This button resets the Host Controller, the PCI logic and restarts the boot process. So it leads to the same result as ON/OFF without Power OFF.

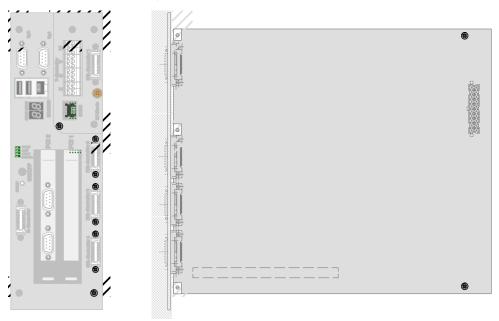
Board Installation

Opening the IPSO AQS

Installation of PCI Cards may require removal the right PCB (next figure) together with the upper part of the front panel. This is possible after removing the screws which are highlighted in the next figure.



Figure 2: Removable screws of the IPSO AQS



Opening the IPSO 19" Unit

The case of the IPSO has to be opened to facilitate controller/PCI card installation. To do that it is only necessary to remove the two screws (right and left) of the top cover next to the front side.

Rules of Modularity on the IPSO 19" Unit

There are two kind of controllers (Rx-Controller and Tx-Controller) which can be plugged into the 9 slots. Some of the slots are dedicated to a unique controller and some stamp a special function on the generic Tx-Controller:

Rx-Controller Slot1 is intended to be used by the Rx-Controller only. But it would

work as receiving controller in any other slot.

Tx-Controller Slot 2 to Slot 9 are designed to be Tx-Controller's places. Plugged into

> Slot 1 the Tx-Controller would be recognized as "unknown" (U-Controller) but it will not be able to communicate with the sequencer and

to transmit data.

Slot 2 Only this slot provides access to the acquisition global functions like

> START, STOP and so on and to the RCP outputs. Therefore the TxController in this slot gets the task of the T-Controller. It controls the RCP outputs instead of its LVDS output. Do not connect a cable to

this LVDS connector. The LED below this connector is always off.

Slot 3 to Slot 9 TxControllers in these slots can work as F-Controller (default) or G-

Controller.

The LED below the LVDS connector lights green at the F-Controller

and yellow at the G-Controller.

The channel numbering of the F-Controller begins at the leftmost one and counts up to the right. There must not be any gap between the

F-Controllers.



Which F-Controller will become the G-Controller?

Only the F-Controller which is connected to a Gradient Amplifier will be configured as G-Controller and its LED below the LVDS connector will change from green to yellow.

Connecting more than one controller to a Gradient Amplifier is not supported by TOPSPIN.

Previous to Rel.2.0, TOPSPIN will only allow the last F-Controller of a system to become the G-Controller. This would be the last one at the right side on "IPSO 19" Unit" and F/G-Controller-4 on "IPSO AOS".

A later release might advantageously allow the G-Controller to be freely selected by connecting the Gradient Amplifier.

Until then an arbitrary F-Controller can be selected as G-Controller if all higher numbered F-Controllers will be logically disabled.

For Example:

You use 3 F-Controllers and 1 G-Controller which is in the slot of FxController-4. If you want to disable the present G-Controller and use FxController-3 instead, you have to

- 1. unplug the LVDS cable from previous G–Controller
- **2.** plug the LVDS cable to FxController–3
- 3. login to IPSO as root
- 4. and run

root@IPSO:/opt/test>sh aqmod.sh -disable fctrl4 ↓

1. 3. Ports

The IPSO services the following Input- and Output Ports





6

Figure 3: Front View of IPSO 19" Unit

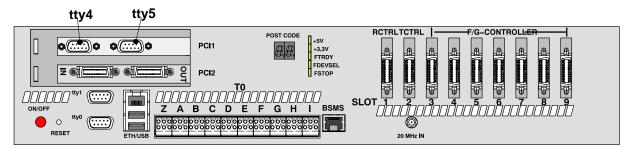
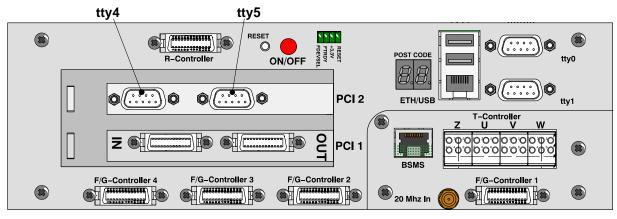


Figure 4: Front View of IPSO AQS



PCI Slots

The two standard PCI slots meet the "PCI Local Bus Specification, Rev.2.1". Both slots are intended for 5–Volt signaling cards (IPSO AQS can accept short cards only).

The total power consumption, summarized for both slots, must not exceed the following values:

IPSO 19" Unit: 10A from +5V and 3.5A from 3.3V

IPSO AQS: 10A from +5V and 5A from 3.3V

Connectors

tty0, tty1: RS232C on ETX module, max. baud rate 115.2Kbaud

The configuration of the tty-interfaces (parity, number of stop bits, kind of handshake, baud rate) is defined and set by the application program.

Type of connector is D-Sub, 9 pin, female

Pin #	Signal	Pin#	Signal	Pin #	Signal
1	RI	4	DTR	7	RTS
2	RxD	5	GND	8	CTS
3	TxD	6	DSR	9	not con.



tty4, tty5: RS232C on auxiliary PCI adapter EX-41052,

max. baud rate 115.2Kbaud

The configuration of the tty-interfaces (parity, number of stop bits, kind of handshake, baud rate) is defined and set by the application program.

Type of connector is D-Sub, 9 pin, female

Pin#	Signal	Pin#	Signal	Pin #	Signal
1	CDC	4	DTR	7	RTS
2	RxD	5	GND	8	CTS
3	TxD	6	DSR	9	RI



ETH 10/100 BaseT, Intel 82551ER

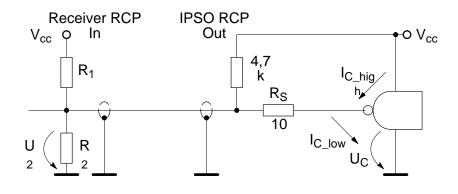
USB USB 1.1 OHCI

The Real Time Pulses (RCP) on Connector T0

Electrical Properties and Constraints of the RCP outputs and receiver inputs

The high and low switching levels (U_2) and the associated current (I_c) of the RCP signals depend on the circuitry and driving capacity of the driver and the circuitry of the connected receiver.

Figure5: RCP Circuit



$$V_{CC} = 5V$$

$$U_{C_low} = 0,3V \\ U_{C_high} = (3,0...3,3)V \qquad U_{2_low/high} = \frac{\left\{V_{CC} + U_{C_low/high} \times \frac{R_1}{R_S}\right\}}{\left\{1 + \frac{R_1}{R_2} + \frac{R_1}{R_S}\right\}} \qquad I_{C_low/high} = \frac{\left\{U_{2_low/high} - U_{C_low/high}\right\}}{R_S}$$

The table shows the resulting voltage levels and currents for some combinations of R_1/R_2 . Other combinations are possible and can be checked by the formulas above.

Table 1: RCP voltage levels and currents

Parameter		Combinations	of Input Circuit		Units
R ₁	100	100	100	200	Ohm
R ₂	68	8	100	200	Ohm
U ₂ if I _C =0	2,0	5,0	2,5	2,5	V
U _{2_low}	0,64	0,73	0,66	0,5	V
U _{2_high}	2,8	3,18	2,91	2,95	V
I _{c_low}	34	43	36	20	mA
I _{c_high}	-20	-12	-30	-25	mA

Signals and Location

IPSO 19" Unit

The signals which are available at the front side connector T0 are:

Type of Signal	Direct.	Name	Count
RCP Output	out	TCU_xy	51
Trigger Input	in	Trig 1,,4	4
Extern Suspend	in	EXT_MAN_SUSP	1
Extern Stop	in	EXT_MAN_STOP	1
Emergency Stop	in/out	EX_SGU_RES	1
Peripheral Status	in	SGU_ST	1
Next Value Clock for Preemphasis	out	EXT_GCLK	1

Another 19 RCP signals (red shadowed in column "T0") are available at connector ST47 inside of the IPSO case.

Figure 6: RCP pin location of IPSO 19" Unit

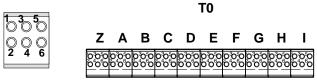


Table 2: Pin assignment of the RCP signals on IPSO 19" Unit

	RCP	and Co	ontrol Sign	als of th	ne T–Co	ntroller	on IPSO 19	" Unit			
Source/ Destina- tion	FIFO Word+ Bit Position (64,,1)		ord+ Bit output reg.		set set nmr nmr 0(#) 3(#)		Layout Name	Di- rec- tion	NM	R	
tion	Α	В	, tout4	U(#)	3(#)	4(#)		tion	Meaning	T0	BS MS
BSMS/ LCB		2	T0(0)		0		TCU62	out	!LOCK_HOLD B1 2		
BSMS/ SCBR		3	T0(1)		1		TCU0	out	!HOMOSPOIL	B2	6
1H Transm.		4	T0(2)		2		TCU1	out	SELH_!H/F B4		
1H Transm.		5	T0(3)		3		TCU2	out	SELX_!X/F B5		
BSMS/ LCB		6	T0(4)		4		TCU3	out	!INT_A_(Z0)	В3	4
BP		7	T0(5)		5		TCU4	out	MIXCC	В6	
		8	T0(6)		6		TCU5	out	res	C1	
HPPR		9	T0(7)		7		TCU6	out	RCP_PA_ SWITCH	C2	
QNP		10	T0(8)		8		TCU7	out	FXA C3		
QNP		11	T0(9)		9		TCU8	out	FXB C4		
		12	T0(10)		10		TCU9	out	res D1		
		13	T0(11)		11		TCU10	out	res	D2	

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	RCP	and Co	ontrol Sigr	nals of the	ne T–Co	ntroller	on IPSO 19	" Unit			
Source/ Destina- tion	Word Pos	FO I+ Bit ition ,1)	tctrl output reg. tout0,	set nmr 0(#)	set nmr 3(#)	set nmr 4(#)	Layout Name	Di- rec- tion	NM	R	
tion	Α	В	, tout4	0(#)	0(#)	4(11)			Meaning	T0	BS MS
		14	T0(12)		12		TCU11	out	res	D3	
		15	T0(13)		13		TCU12	out	res	D4	
		16	T0(14)		14		TCU13	out	res	D5	
		17	T0(15)		15		TCU14	out	res	D6	
		18	T1(0)		16		TCU15	out	res	G1	
		19	T1(1)		17		TCU16	out	res	G2	
		20	T1(2)		18		TCU17	out	res	G3	
		21	T1(3)		19		TCU18	out	res	G4	
		22	T1(4)		20		TCU19	out	res	G5	
		23	T1(5)		21		TCU20	out	res	G6	
		24	T1(6)		22		TCU21	out	res	H1	
		25	T1(7)		23		TCU22	out	res	H2	
MED		26	T1(8)		24		TCU23	out	ECG_START_ TRIG	НЗ	
MED		27	T1(9)		25		TCU24	out	AUT_TUNG_ IN	H4	
MED		28	T1(10)		26		TCU25	out	AKTIV_ DEC_RES	H5	
MED		29	T1(11)		27		TCU26	out	AK- TIV_DEC_RE S	H6	
MED		30	T1(12)		28		TCU27	out	Customer specified	l1	
MED		31	T1(13)		29		TCU28	out	Customer specified	12	
MED		32	T1(14)		30		TCU29	out	Customer specified	13	
MED		33	T1(15)		31		TCU30	out	Customer specified	14	
		34	T2(0)			0	TCU31	out	GAIN_0_TR1	ST47 pin 1	
		35	T2(1)			1	TCU32	out	GAIN_1_TR1	ST47 pin 3	
		36	T2(2)			2	TCU33	out	C/AB_TR1	ST47 pin 5	
		37	T2(3)			3	TCU34	out	GAIN_0_TR2	ST47 pin 7	
		38	T2(4)			4	TCU35	out	GAIN_1_TR2	ST47 pin 9	
		39	T2(5)			5	TCU36	out	GAIN_2_TR2	ST47 pin 11	

	RCP	and Co	ontrol Sigr	nals of th	ne T-Co	ntroller	on IPSO 19	" Unit			
Source/ Destina- tion	Word Pos	FO d+ Bit ition ,1)	tctrl output reg. tout0,	set nmr 0(#)	set nmr 3(#)	set nmr 4(#)	Layout Name	Di- rec- tion	NM	R	
	Α	В	, tout4		J (,,)	-(")			Meaning	ТО	BS MS
		40	T2(6)			6	TCU37	out	GAIN_2_TR1	ST47 pin 13	
1H1 KW AMPL		41	T2(7)			7	TCU38	out	RELAY_H	E3	
X1 KW AMPL		42	T2(8)			8	TCU39	out	RELAY_X	E4	
X1 KW AMPL		43	T2(9)			9	TCU40	out	RELAY_Y	E5	
		44	T2(10)			10	TCU41	out	res RACK_ON/ OFF	E6	
		45	T2(11)			11	TCU42	out	RCP	F1	
X1 KW AMPL		46	T2(12)			12	TCU43	out	RELAY Z	F2	
		47	T2(13)			13	TCU44	out	RCP_Scope	F3	
		48	T2(14)			14	TCU45	out	RCP_EXT_ DEV	F4	
		49	T2(15)			15	TCU46	out	RCP	F5	
HIGH POWER		50	T3(0)			16	TCU47	out	STP1_DIR	ST47 pin 15	
HIGH POWER		51	T3(1)			17	TCU48	out	LB_SEL	ST47 pin 17	
HIGH POWER		52	T3(2)			18	TCU49	out	DCM_STRT	ST47 pin 19	
HIGH POWER		53	T3(3)			19	TCU50	out	STP1_CLK	ST47 pin 21	
HIGH POWER		54	T3(4)			20	TCU51	out	STP2_CLK	ST47 pin 23	
HIGH POWER		55	T3(5)			21	TCU52	out	RES_STP1	ST47 pin 25	
HIGH POWER		56	T3(6)			22	TCU53	out	DCM_RES	ST47 pin 27	
HIGH POWER		57	T3(7)			23	TCU54	out	GO_POS	ST47 pin 29	
2H Lock Switch		58	T3(8)			24	TCU55	out	SEL_2H AMP and TUNE_MODE in MRIs only	A1	
		59	T3(9)			25	TCU66	out	res	ST47 pin 31	
		60	T3(10)			26	TCU57	out	res	Z2	
		61	T3(11)			27	TCU58	out	Q_SWITCH and SCO/CCO in MRIs only	А3	

	RCP	and Co	ontrol Sigr	nals of the	he T-Co	ntroller	on IPSO 19	" Unit			
Source/ Destina- tion	Word Pos	FO I+ Bit ition ,1)	tctrl output reg. tout0,	set nmr 0(#)	set nmr 3(#)	set nmr 4(#)	Layout Name	Di- rec- tion	NM	R	
tion	Α	В	, tout4	0(#)				11011	Meaning	T0	BS MS
2H Lock Switch		62	T3(12)			28	TCU59	out	SEL_!X/2H and REF_MODE in MRIs only	A2	
		63	T3(13)			29	TCU60	out	res	F6	
		64	T3(14)			30	TCU61	out	res	15	
	58		T3(15)			31	TCU56	out	res	16	
GRASP	59		T4(0)	32			TCU63	out	BLK_GRAD_ X	A4	
GRASP	60		T4(1)	33			TCU65	out	BLK_GRAD_ Y	A5	
GRASP	61		T4(2)	34			TCU64	out	BLK_GRAD_ Z	A6	
	62		T4(3)				TCU67	out			
	63		T4(4)				TCU68	out			
	64		T4(5)				TCU69	out			
BP HR MAS							TRIG1	in	Trigger 0	C5	
BSMS SLCB							TRIG2	in	Trigger 1	C6	
TRIG STRAFI							TRIG3	in	Trigger 2	E1	
TRIG Solid MAS							TRIG4	in	Trigger 3	E2	
Ext. But- ton							EXT_MA N_SUSP	in	Manual Sus- pend	Z5	
Ext. But- ton							EXT_MA N_STOP	in	Manual Stop	Z6	
							EX_SGU _RES	in/out	Emergency Stop	Z3	
SGU							SGU_ST	in	STATUS	Z4	
DPP							EXT_GC LK	out	NEXT VALUE	Z1	
							GND				1,3, 5

IPSO AQS

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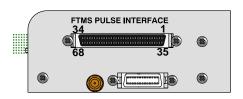
The signals which are available at the front side connector T0 are:

Type of Signal	Direct.	Name	Count
RCP Output	out	TCU_xy	14
Trigger Input	in	Trig 1,,4	4

Type of Signal	Direct.	Name	Count
Extern Suspend	in	EXT_MAN_SUSP	1
Extern Stop	in	EXT_MAN_STOP	1
Emergency Stop	in/out	EX_SGU_RES	1
Peripheral Status	in	SGU_ST	1
Next Value Clock for Preemphasis	out	EXT_GCLK	1

Another 3 RCP signals are available at the RJ-45 connector, labeled "BSMS"

Table 3: RCP outputs, versions FTMS and NMR



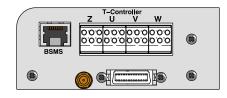




Table 4: Pin assignment of the RCP signals on IPSO AQS

	RCP and Control Signals of the T-Controller on IPSO AQS													
Sourc e/Des-	FIF Wor Bit P tic (64,	rd+ Posi- on	tctrl outp reg.	set nmr	set nmr	set nmr	Layout	Di- rec-	NM	R		FTMS		
tina- tion	A	В	tout0, , tout4	0(#)	3(#)	4(#)	Name	tion	tion	Meaning	то	B S M S	Meaning	amp 68
BSMS/ LCB		2	T0(0)		0		TCU62	out	!LOCK_ HOLD		2	User ■Pulse 0	5	
BSMS/ SCBR		3	T0(1)		1		TCU0	out	!HOMO SPOIL		6	User ■Pulse 1	6	
1H Trans m.		4	T0(2)		2		TCU1	out	SELH_!H/F	U2		User Pulse 2	7	
1H Trans m.		5	T0(3)		3		TCU2	out	SELX_!X/F	U3		User ■Pulse 3	8	
BSMS/ LCB		6	T0(4)		4		TCU3	out	!INT_A_ (Z0)		4	User ■Pulse 4	9	
HPPR		9	T0(7)		7		TCU6	out	RCP_PA_ SWITCH	U4				
		12	T0(10)		10		TCU9	out	res	U5				
		13	T0(11)		11		TCU10	out	res	U6		Combi Laser Pulse	10	
		14	T0(12)		12		TCU11	out	res	W2		IRMPD Laser Pulse	11	
		15	T0(13)		13		TCU12	out	res	W4		Q Source Shutter	12	

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IPSO AQS

RCP and Control Signals of the T-Controller on IPSO AQS **FIFO** Word+ tctrl Bit Posi-**NMR FTMS** Sourc outp tion set set Diset e/Desreg. (64,...,1) Layout nmr nmr nmr rectinatout0, Name 4(#) 0(#) 3(#) tion tion S amp tout4 Α В Meaning T0 Meaning М 68 S Q Hexa-T0(14) 14 TCU13 W6 13 16 out res pol Deflection Q Hexa-TCU14 T0(15) 15 pol Accu-14 17 out res mulation ICC/ICE 20 TCU19 22 T1(4) Step 15 out res Pulse LC MS/ 23 T1(5) 21 TCU20 out MS Polar-16 res ity Pulsed T1(6) 22 TCU21 24 17 out res Valve 1 Combi TCU22 25 T1(7) 23 out res Pulsed 18 Valve2 ECG_STAR **DEFLEC-**TCU23 MED 26 T1(8) 24 out 19 T_TRIG TION Aux **AUT_TUN DEFLEC-**MED 27 T1(9) 25 TCU24 out 20 G_IN TION AK-INT GAT TIV_DEC_ MED 28 T1(10) 26 TCU25 out 21 Ε **RES** AK-TIV_DEC_ MED 29 T1(11) 27 TCU26 out QUENCH 22 RES HFU RX Customer TCU27 MED 30 T1(12) 28 out SW_ 23 specified **GAIN** HFU RX Customer MED T1(13) 29 TCU28 out REC_ 24 specified EXEC HFU RX Customer ADC_IN_ MED 32 T1(14) 30 TCU29 25 out specified SEL Customer Pulsed TCU30 MED 33 T1(15) 31 out 26 Valve 3 specified 1H1 **AMPL** KW T2(7) 7 TCU38 RELAY_H W1 27 41 out **BLANK AMPL** X1 KW User TCU39 RELAY_X W3 28 42 T2(8) 8 out **AMPL** Pulse 5 X1 KW User 9 TCU40 RELAY_Y W5 29 43 T2(9) out **AMPL** Pulse 6

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			RCP	and C	ontrol	Signal	s of the T	-Contr	oller on IPSO	AQS				
Sourc e/Des-	FIFO Word+ Bit Posi- tion (64,,1)		tctrl outp reg.	set nmr	set nmr	set nmr	Layout	Di- rec-	NMR			FTMS		
tina- tion	A	В	tout0, , tout4	0(#)	3(#)	4(#)	Name	tion	Meaning	то	B S M S	Meaning	amp 68	
X1 KW AMPL		46	T2(12)			12	TCU43	out	RELAY_Z			User Pulse 7	30	
		47	T2(13)			13	TCU44	out	RCP_ Scope	V5				
		48	T2(14)			14	TCU45	out	RCP_EXT_ DEV	V6				
2H Lock Switch		58	T3(8)			24	TCU55	out	SEL_ 2H AMP	U1		User ■Pulse 8	31	
	58		T3(15)			31	TCU56	out				MALDI Pulsed Valve	32	
BP HR MAS							TRIG1	in	Trigger 1	V1		Trigger 1	1	
BSMS SLCB							TRIG2	in	Trigger 2	V2		Trigger 2	2	
TRIG STRAF I							TRIG3	in	Trigger 3	V3		Trigger 3	3	
TRIG Solid MAS							TRIG4	in	Trigger 4	V4		Trigger 4	4	
									res	Z2				
Ext. Button							EXT_ MAN_ SUSP	in	Manual Suspend	Z 5				
Ext. Button							EXT_ MAN_ STOP	in	Manual Stop	Z6				
SGU							EX_S GU_R ES	in/ out	Emergency Stop	Z3				
SGU							SGU_ ST	in	STATUS	Z4				
DPP							EXT_G CLK	out	NEXT VALUE	Z1				
							GND				1,3 ,5			

1. 4. Boot Operation

A successful boot operation requires the ethernet connection to the powered TOPSPIN–PC which services a valid "diskless", the correct BIOS adjustments on the "IPSO Host Controller" and pushing the Power–On button for about 2 seconds.

The successful completion of the boot process can be checked in TOPSPIN by typing

ha

or in a LINUX shell by typing

/opt/topspin/prog/bin/scripts/GetSpectDev -i

Both methods return the IP-Address of the connected IPSO.

The boot process is automatically controlled by the DHCP process. Normally there is nothing to configure and thus nothing to set incorrectly. The causes of an unsuccessful boot process can only be:

- LAN Boot in BIOS not enabled. To enable the LAN Boot feature would require the connection of a monitor and a keyboard to the IPSO
- A corrupted "diskless" on the TOPSPIN-PC, which should be installed again
- A hardware error, which would necessitate further investigation of the boot process to get some more information.

Investigating the Boot Process

Additional information about the boot process can be obtained from 3 sources and from different phases of the boot sequence

- **1.** By monitoring the POST code display and beep codes (requires no additional resources)
- **2.** By configuring the Hyper Terminal application (Windows) or the "cu" application (LINUX) on the TOPSPIN–PC.

(Shows messages of bootloader and LINUX)

3. By connecting a monitor and a keyboard to the IPSO (Shows all messages during the boot process and provides access to the BIOS adjustments)

POST Code Display

The Power–on–self–test and configuration routines (POST) start just after Power–on. The POST code points to the individual parts which are currently just running or have stopped in case of an error. This sequence normally ends after about 20 seconds with "C0 = Trying to boot OS"

The list of references between POST codes and routines may be found in the addendum or can be loaded from the webside of "PHOENIX Technologies Ltd" (PhoenixBIOS 4.0, Rev.6).

The POST code display is undefined after start of Linux.

Occasionally occurred BIOS errors:

POST Code	POST Routine	Possible Causes	Recommended Actions
28	Auto size DRAM	DRAM error	1.Check insertion of the DRAM in the socket 2.Exchange DRAM or PC–Module
		Faultily inserted PC–Mod- ule (Host Controller)	1.Check insertion of the PC–Module
49	Unsuccessful PCI configuration	Any defective Tx- or RxController in the system	2.Remove the controllers one after the other and try again 3.Check voltages of the Power Supply
		Defective RESET sequence	4.Exchange the PC–Module

POST Code	POST Routine	Possible Causes	Recommended Actions
60	Check extended memory	Normal BIOS routine which takes about 10 seconds; the duration is dependend on the volume of memory	If the test doesn't finish, check the correct fit of the memory.
98	Search for any extention ROM	Normal BIOS routine which takes only a few seconds	If the test doesn't finish, check the correct fit of the PC–Module and any PCI–Connection.
ВО	Check for errors, stops at B0 with 2 beeps in case of error	The timer containes cor- rupted time and date infor- mation.	To recover the content of the timer: 1. Press the RESET button or 2. Connect an USB–keyboard and press F1 to resume and correct time and date with LINUX or 3. Connect a monitor too, press F2 to enter the BIOS setup and correct the time and date or set "Hold on errors" to "NO"
CO	Try to boot	Successful BIOS process but "No Operating System found"	1.Check Ethernet connection. Yellow LINK LED on? Green Rx/Tx LED active? 2.Check in BIOS if Netboot=yes? (see below) or Netboot is at the top of the list in the submenu "Boot Device Priority" and set the item "Onboard LAN PXL ROM" to "Enabled"

Note:

The PC–Module can be pulled off after removing the 4 screws on top

of the Module.

To check or exchange the DRAM, the module has to be opened after

removing the 2 screws at its bottom side.

Acoustic Beep Codes

Additional to the POST code display some POST routines sound a beep code on error. This beep code is derived from the hexadecimal POST code of the failing test as follows:

- **1.** The 8-bit error code is broken down to four 2-bit groups.
- **2.** Each group is made one–based (1 through 4) by adding 1.
- **3.** Short beeps are generated for the number in each group.

Example: POST code $16h = 00\ 01\ 01\ 10 = 1-2-2-3$ beeps

The "Hyper Terminal" or "cu" window

The boot messages of the IPSO-OS (LINUX) can be printed in a window of the TOPSPIN-PC. This needs a RS232 connection from tty0 of IPSO to a COM port of the TOPSPIN-PC. For details see the TOPSPIN Installation Guide.

Monitor and Keyboard at IPSO

The most detailed information about the boot process can only be obtained by connecting an additional monitor and a keyboard to the connectors inside of the case. It is then possible to watch the BIOS and Linux Messages during the boot sequence and to enter the BIOS setup utility.

Boot Sequence

	Phase of Boot Sequence	Post Code	POST Beeps	Operation
1.	Power On			
		16h	1-2-2-3	Check BIOS ROM checksum
		20h	1-3-1-1	Test DRAM refresh
		22h	1-3-1-3	Test 8742 Keyboard Controller
		2Ch	1-3-4-1	RAM failure on address line xxxx*
		2Eh	1–3–4–3	RAM failure on data bits xxxx* of low byte of memory
		30h	1-4-1-1	RAM failure on data bits xxxx* of high byte of memory
2.	Running POST Code	46h	2-1-2-3	Check ROM copyright notice
	real ming r CO1 Codo	4Ah		
		58h	2-2-3-1	Test for unexpected interrupts
		59h		
		6Eh		
		87h		
		98h	1–2	Search for option ROMs
		B0h	1–1	Halt on error
		C0h		Try to boot
3.	DHCP Process			IPSO applies for an IP address at the DHCP server
				Load and Start of Bootloader
4.	Running Boot Loader			First message sent to the Hyper Terminal window from Boot Loader
5.	Loading the OS			Boot messages of Linux in Hyper Terminal

Checking the BIOS Setup

This requires a monitor and a keyboard at IPSO.

The majority of BIOS items should retain their default values. The complete list of items and its values can be found in the "Addendum".

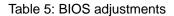
To show the BIOS version press the Pause key after start of booting.

To investigate and modify the BIOS adjustments start the BIOS setup utility by pressing F2 when the following string appears during bootup.

Press <F2> to enter Setup

Note: Selecting incorrect values may cause boot failures. Load setup–default

values to recover by pressing <F9>



Entry	Meaning	Phönix BIOS 4.0, Rel. 6.0
Kontron-Version		MOD9R111
Network boot support?		yes

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Entry	Meaning	Phönix BIOS 4.0, Rel. 6.0
Display Control → Flat Panel Type		Auto Detect
PNP OS Installed	PCI Bridge Support	no
Onboard LPT	Used for JTAG	enable
Legacy USB Support	Global, Interface 0+1, extern	enable
On Chip USB 2 Device	Interface 2+3, intern to Slot A+B	disable
PCI Configuration → PCI IRQ Line1	IRQ select for Line "w"	Auto Select
PCI Configuration → PCI IRQ Line2	IRQ select for Line "x"	Auto Select
PCI Configuration → PCI IRQ Line3	IRQ select for Line "y"	Auto Select
PCI Configuration → PCI IRQ Line4	IRQ select for Line "z"	Auto Select

1. 5. System Configuration

System configurations of this context means:

- 1. During boot the BIOS checks for available hardware on the PCI bus, e.g. inserted controller or PCI cards. It recognizes the bus layout, scans all possible slots (sites) for devices, reads the type of the devices and their required amount of address space, defines and sets the base address of each device, lists all devices found and determines which interrupt line they are connected to.
- 2. After boot, the AQ-Driver uses the list of the BIOS, reads some additional registers of some devices and gains the necessary information to decide on which IPSO host model (IPSO 19" Unit or IPSO AQS) the software is coming up.

There is no active role for the user to influence this process other than changing the arrangement of inserted controllers and PCI cards. And normally this should not be necessary.

Modifying the arrangement changes the device number of each device and could alter the following situations:

- Which controllers can communicate with each other without having to go over a bridge. This is normally irrelevant.
- Which of the controllers share the same interrupt line with each other and with other devices, e.g. the Ethernet or the tty ports.
- To which priority level of the interrupt controller (there are 15) the interrupt of a device has been routed

The PCI bus contains 4 interrupt lines (INTw, INTx, INTy, INTz named in BIOS as Line 1, Line 2, Line 3, Line 4). The distribution of each controller slot interrupt to one of these lines is hard wired.

Table 6: Interrupt distribution of the IPSO 19" Unit

		Controller Slot											
	1	2	3	4	5	6	7	8	9	DOI 4	D		
	rctrl	tctrl	fctrl 1	fctrl 2	fctrl 3	fctrl 4	fctrl 5	fctrl 6	fctrl 7	PCI 1	PCI 2		
Line 1	х					х							
Line 2				х	х				х				
Line 3			Х					Х		Х			
Line 4		х					х				х		

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Table 7: Interrupt distribution of the IPSO AQS

		Controller Slot												
	rctrl	tctrl	fctrl 1	fctrl 2	fctrl 3	gctrl	PCI 1	PCI 2						
Line 1			х					х						
Line 2		х				х								
Line 3					х									
Line 4	х			х			х							

The decision about routing of Line 1/2/3/4 to any of the interrupt priority levels (IRQ) and sharing them with further interrupt sources is made by the BIOS, provided the BIOS parameter "PCI IRQ Line" is set to "Auto Select". These routings can be checked in a LINUX shell with:

cat /proc/interrupts

We do not recommend replacing "Auto Select" by a special IRQ level.



	higl	nest	Interrupt Priority Order lowest												est
IRQ	0	1	8	9	10	11	12	13	14	15	3	4	5	6	7

Recognition of the host model

Recognition of the host model and the version of the installed controller will be performed by the AQ–Driver of LINUX in following steps:

- 1. Search for a PLX device with Subdevice–ID = 0x0200 and the IMBF version register implemented.
- **2.** Read the content of the IMBF version register
- 3. If IMBF=0xFFFF or 0x0000, > IPSO 19" Unit
 - 1. Read the version register SLOT_BRDV on each Controller
 - **2.** SLOT_BRDV=0xXFXX or 0xX0XX > 2MB external RAM on this Controller and DSP TMS320C6415

SLOT_BRDV=0xX1XX > 16MB external RAM on this Controller and DSP TMS320C6415

SLOT_BRDV=0xX2XX > 128MB external RAM on this Controller and DSP TMS320C6455

- **4.** If IMBF= 0x0001, > IPSO AQS > IPSO AQS HOST including RxController with 2MB external RAM and DSP TMS320C6415
 - 1. Read the board version of IPSO AQS ACQ out of the T_BRDV register
 - 2. T_BRDV=0x0000 > Tx-Controller with 16MB external RAM and DSP TMS320C6415 on IPSO AQS ACQ
 - **3.** T_BRDV=0x0200 > Tx-Controller with 128MB external RAM and DSP TMS320C6455 on IPSO AQS ACQ

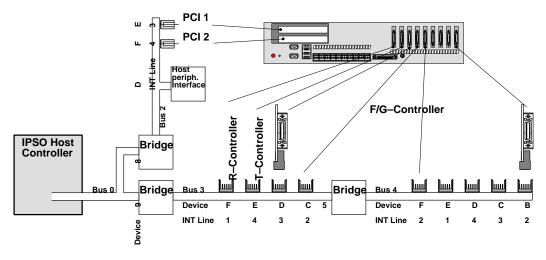
IPSO AQS

Table8: IPSO Versions

IPSO Manual

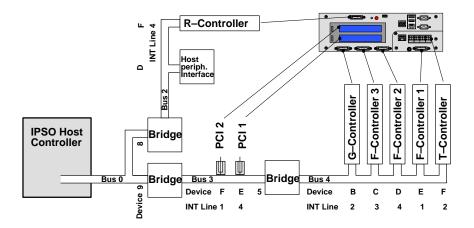
	IM	BF		T _l	BRDV		5	SLOT_	BRD	V	
V	ariatio	ns	mo del	rev.	sub	rev.	slot	ver sn.	su	bv.	
F	F	F	F								1000 400 11 11
0	0	0	0								IPSO 19" Unit
							Х	F	Χ	Χ	Tx-Controller of IPSO 19 Unit
				no	used		Х	0	Х	Х	ext RAM 2MB, DSP TMS320C6415
							Х	X 1 X X		Χ	Tx-Controller of IPSO 19" Unit ext RAM 16MB, DSP TMS320C6415
							Х	2	Х	Х	Tx-Controller of IPSO 19" Unit ext RAM 128MB, DSP TMS320C6455
											IPSO AQS HOST, Rx-Controller with ext. RAM of 2MB, DSP TMS320C6415
0	0	0	1	0 0	0	0	-	not (used		IPSO AQS ACQ, 5 Tx-Controller, ext. RAM 16MB, DSP TMS320C6415
				0 2	0	0					IPSO AQS ACQ, 5 Tx-Controller, ext. RAM 128MB, DSP TMS320C6455

Figure7: Host bus of the IPSO 19" Unit



Note: Inserting PCI cards with on–board bridges implies adding further bus segments which can in turn change the bus numbers!

Figure8: Host bus of the IPSO AQS



Note: Inserting PCI cards with on–board bridges implies adding further bus segments which can in turn change the bus numbers!

Checking the Configuration

Modification of the system (by inserting or removing controllers or PCI cards) should always be followed by checking the system–recognized structure against the expected one. For instance, "has the system accurately recognized the number and the type of all inserted controllers?".

Starting the ipsotest when logged in at the IPSO

```
root@IPSO:/opt/test>ipsotest →
```

returns a list of all recognized controllers, their bus and device numbers and their application specific utilization. Bus bridges, general PCI devices and interrupt routings are not shown.

A complete list of all PCI devices and interrupt routings is shown by typing

```
root@IPSO:/opt/test>cat /proc/pci →
```

Note: Devices on bus0 and bus1 are not application relevant!

1. 6. Power Supply

Checking Temperature and Voltages

Typing "mbmon –A" when logged in at the IPSO

```
root@IPSO:/opt/test>mbmon -A↓
```

returns something like the following values provided by voltage and temperature sensors:

On IPSO 19" Unit

Temp.=	82.0	80.5	80.5			(so far, June 2006, these values are not correct)
		next to the	next to the	Voltage Re	egulators	Sensor location on the IPSO Base Board
	below the	ļ	oller (PC-M		Gensor location on the if GO base Board	
Rot.=	0	0	0			Fan speed; not implemented
Vcore=	1.30	3.41				Core voltage of the Host Controller
Volt.=	3.41	5.03	12.46	-11.87	-5.25	Voltages of the Power Supply

Note: The –5Volt from Power Supply is not used!

On IPSO AQS

Temp.=	82.0	80.5	80.5			(so far, these values are not correct)
			next to the	Rx-Control	ller	Sensor location on IPSO AQS HOST
		next to the	PCI conne	ctor		Sensor location on IPSO AQS ACQ
	below the	Host Contro	oller (PC-M	odule)		Sensor location on IPSO AQS HOST
Rot.=	0	0	0			Fan speed; not implemented
Vcore=	1.30	3.41				Core voltage of the Host Controller
Volt.=	3.41	5.03	12.46	-11.87	-5.25	Voltages of the Power Supply

Power Conditions on the IPSO 19" Unit

Currents and Voltages

Part-No.	Assembly		+5V	Σ +5 V	+3,3V	+12V	+5VSB	–12V
H12519	IMB	ETX 400Mhz + IMB		2,5 A	2,5 A	0,1	(1,8A)	0,1
		2 PCI Slot (25W)		10 A				
		70 RCP/30 mA		2,1A				
H12538xx	Tx-Controller	1x(0,3+0,3)	0,6 A		0	0		0
		8x		4,8 A	0	0		0
H12532xx	Rx-Controller	1x	0,6 A	0,6 A	0	0		0
Current required from ATX Power Supply				20,0 A	2,5 A	0,1 A	(1,8A)	0,1 A
Power				108,25 W				
				109,45 W				

Used Power Supply

Any ATX Power Supply with the same Formfactor would meet the functional requirements. But to keep the excellent quality and the mark of conformity valid, only the type

eNSP-300P-S20-00S

of the manufacturer Nipron has to be used for a replacement.

This installed type is ATX Version 2.03 compliant with 20–Pin Power Connector. Since –5Volt are not required, Power Supplies with 24–Pin Connectors (ATX12V Version 2.2) also meet the requirements but need an adapter.

The Nipron Power Supplies are said to run 24 hours a day during 10 years.

The Reliability Grade is "Factory Automation" instead of "Office Automation".

The Fan can be replaced without disassembling either the Power Supply or the IPSO.

General Specifications		Continuous Output Specifications						
General Sp	+5V	+3.3V	+12V	+5VSB	-12V			
Part-No.	87451	21 A	14 A	10A	1,5 A	0,8 A		
Manufacturer	Nipron	125 W						
Туре	eNSP-300P-S20-00S	185 W						
Continuous Power	200W			203 W				
Peak Power	300W							
Input	AC85~264V							
MTBF	100,000 hours							
Safety Standard	UL, CSA(c-UL), EN, CE							

Power Conditions on the IPSO AQS

Currents and Voltages

Part-No.	Assembly		+5 VSB	Σ +5 V	+3,3 V	+12 V	–12 V	analog +5V
H12549	IPSO AQS ACQ	5x TxCon- troller			5x0,6 A			
		28 RCP		0,9 A				
		Generation of 2,5 V			1,5 A			
Sum of ACQ			0,9 A	4,5 A				
H12547	IPSO AQS Host	ETX 400Mhz	1,5A	2,5 A	1,6 A	0,1 A	0,1 A	
		RxController			0,6 A			
		2 PCI Slot (25W)		10 A				
Sum of IPSO AQS			13,4 A	6,7 A	0,1 A	0,1 A		
Supplied to AQS/3			8,2A		6,7A	0,01A	6,9A sepa- rated GND	
Required from Power Supply		1,5 A	21,6 A	6,7 A	6,8 A	0,11 A	6,9 A	

Used Power Supply

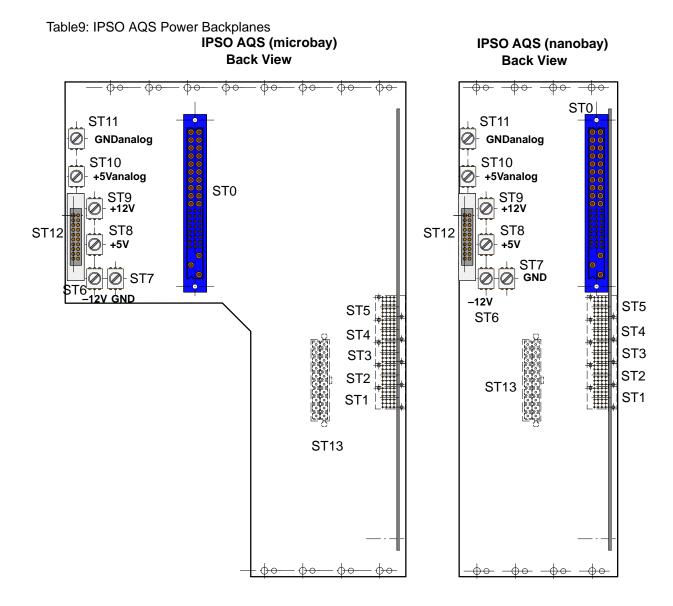
The Power Supply of the IPSO AQS is a VME–Bus power module with a Formfactor of 12TE/6HE. This module is a special design of GERMAN POWER and can not be replaced by any commercially available device.

This Power Supply meets "ATX Power Supply Design Guide, Version 2.2" except for necessary variations like form, currents, voltages and connectors.

The Power Supply has to be cooled from outside (no fan inside).

		Continuous Output Specifications						
General Sp	+5VSB	+5V	+3.3V	+12V	-12V	analog +5V		
Part-No.		2,0 A	25,7 A	12,1 A	10A	0,2 A	10 A	
Manufacturer	German Power							
Туре	BSAA350-230W-6							
Continuous Power 350W		350W						
Peak Power								
Input	AC100~240V							
Safety Standard	EN, IEC, UL, CSA(c-UL), CE							

IPSO AQS Power Backplane



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